## **GATE CLOUD**

# **SIGNALS & SYSTEMS**

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R. K. Kanodia Ashish Murolia

## **JHUNJHUNUWALA** Jaipur

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The book is categorized into eleven chapters covering all the topics of syllabus of the examination. Each chapter contains :

- Exercise 1 : Theoretical & One line Questions
- Exercise 2 : Level 1
- Exercise 3 : Level 2
- Exercise 4 : Mixed Questions taken form previous examinations of GATE & IES.
- Detailed Solutions to Exercise 2, 3 & 4
- Summary of useful theorems

Although we have put a vigorous effort in preparing this book, some errors may have crept in. We shall appreciate and greatly acknowledge the comments, criticism and suggestion from the users of this book which leads to some improvement.

Wish you all the success in conquering GATE.

Authors

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# GATE CLOUD DIGITAL ELECTRONICS

R. K. Kanodia & Ashish Murolia

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# CHAPTER 1

## **CONTINUOUS TIME SIGNALS**

# **EXCERCISE 1.1**

MCQ 1.1.1	The graphical representation of a signa (A) frequency	l in the time domain is known as (B) waveform
	(C) frequency spectrum	$(\mathbf{D})$ none of the above
	(c) nequency spectrum	
MCQ 1.1.2	A continuous-time signal is a signal in (A) discrete	which the independent variable is (B) continuous
	(C) (A) or (B)	(D) none of the above
MCQ 1.1.3	Digital signals are those signal which (A) do not have a continuous set of val (B) have values at discrete instants (C) can utilize decimal or binary system (D) are all of the above	ues n
MCQ 1.1.4	<ul> <li>A deterministic signal is the signal white</li> <li>(A) can not be represented by a mathematical (B) has no uncertainty</li> <li>(C) has uncertainty</li> <li>(D) none of the above</li> </ul>	ch matical expression
MCQ 1.1.5	A random signal is the signal which (A) has uncertainty (C) is a completely specified function o	<ul><li>(B) has no uncertainty</li><li>(D) none of the above</li></ul>
MCQ 1.1.6	<ul> <li>Speech signals and the sine wave respect</li> <li>(A) deterministic signal, random signal</li> <li>(B) both random signals</li> <li>(C) both deterministic signals</li> <li>(D) random signal, deterministic signal</li> </ul>	ctively are the example of  s
MCQ 1.1.7	Which of the following is a periodic sign (A) $x(t) = At^2$ (C) $x(t) = Ae^{\alpha t}$	nal ? (B) $\frac{x(t) = Ae^{-j\alpha t}}{x(t) = Au(t)}$

Page 4	Continuous	Time Signals	Chapter 1
MCQ 1.1.8	The sum of two periodic signals ratio of their respective periods ( (A) an irrational number (C) an odd number	having periods $T_1$ and $T_2$ is per $T_1/T_2$ ) is (B) a rational number (D) an even number	iodic only if the
MCQ 1.1.9	<ul> <li>A continuous-time signal x(t) is sawhere T<sub>0</sub> is the</li> <li>(A) smallest positive integer satisfying the integer m.</li> <li>(B) positive constant satisfying the integer m.</li> <li>(C) largest positive constant satisfy any integer m</li> <li>(D) smallest positive constant satisfy and any integer m</li> </ul>	aid to be periodic with a fundam fying the relation $x(t) = x(t + m$ ne relation $x(t) = x(t + mT_0)$ for fying the relation $x(t) = x(t + m$ isfying the relation $x(t) = x(t + m$	ental period $T_0$ , $T_0$ ) for any $t$ and every $t$ and any $T_0$ ) for any $t$ and $mT_0$ ) for every $t$
MCQ 1.1.10	Sine waves, cosine waves, square (A) non-deterministic functions (C) periodic functions	waves and triangular waves are t (B) multiple frequency fu (D) all of the above	he examples of inctions
MCQ 1.1.11	A signal is given by $x(t) = 2\cos \theta$ odd component of $x(t)$ is (A) $\cos(\omega t)\sin^2(\omega t)$ (C) $\sin^2(\omega t)$	$(\omega t)\sin^2(\omega t) + 2\cos(\omega t) + \sin\omega(t)$ (B) $\sin(\omega t)$ (D) $\cos(\omega t)$	$) + \sin^2(\omega t)$ . The
MCQ 1.1.12	f(t) is even while $g(t)$ is odd. If $x$ , y(t) are respectively (A) neither, even (C) neither, odd	f(t) = f(t) + g(t) and $y(t) = f(t)g(t)(B) odd, even(D) even, odd$	(t) then $x(t)$ and
MCQ 1.1.13	Signal $x(t) = 5 \sin 20\pi t$ (A) is an even signal (C) has even and odd parts	<ul><li>(B) is an odd signal</li><li>(D) none of the above</li></ul>	
MCQ 1.1.14	<ul> <li>Which of the following statements</li> <li>1. The product of two even sign</li> <li>2. The product of two odd signs</li> <li>3. The product of even and odd</li> <li>4. The product of even and odd</li> <li>(A) 2 and 3</li> <li>(C) 3 only</li> </ul>	s is not true ? als in an even signal als in an odd signal. signals in an even signal. signal is an odd signal. (B) 1 only (D) 4 only	

MCQ 1.1.15	$x(t) = 5\sin\left(10\pi t + 30^\circ\right)$	
	(A) is an odd signal	
	(B) is an even signal	
	(C) has an even part as well as an odd p	part
	(D) none of the above	
MCQ 1.1.16	The signal $x(t) = 10e^{j10\pi t}$ is	
	(A) an energy signal	(B) a power signal
	(C) neither energy nor power signal	(D) both energy and power signal
MCQ 1.1.17	Signal $e^{-2t}u(t)$ is	
	(A) a power signal	
	(B) an energy signal	
	(C) neither an energy signal nor a power	r signal
	(D) none of the above	
MCQ 1.1.18	A signal is an energy signal if it has	
	(A) infinite energy	(B) finite energy
	(C) zero average power	(D) both (B) and (C)
MCQ 1.1.19	A signal is a power signal if it has	
	(A) infinite energy	(B) infinite power
	(C) finite power	(D) both (A) and (C)
MCQ 1.1.20	The signal $A\cos(\omega_0 t + \phi)$ is	
	(A) a periodic signal	(B) a power signal
	(C) both periodic and power signals	(D) a energy signal
MCQ 1.1.21	Which of the following is an energy sign	al ?
	(A) $x(t) = A \cos \omega_0 t$	(B) $x(t) = A \sin \omega_0 t$
	(C) $x(t) = A e^{j\omega_0 t}$	(D) $x(t) = e^{-at}u(t)$
MCQ 1.1.22	Which of the following statement are tru	ie ?
	1. Most of the periodic signals are energy	rgy signals.
	2. Most of the periodic signals are pow	er signals.
	3. For energy signals, the power is zero	).
	4. For power signals, the energy is zero	).
	(A) $1, 2$ and $3$ only	(B) 1 only
	(C) 1 and 2 only $($	(D) $1, 2, 3, and 4$

Page 6	Continuous Time Si	gnals	Chapter 1
MCQ 1.1.23	A complex valued signal $x(t) = x_R(t) + j$ (A) $x_R(t)$ is odd while $x_I(t)$ is even (C) $x_R(t)$ is even while $x_I(t)$ is odd	$x_I(t)$ has conjugate symmetry if (B) $x_R(t)$ and $x_I(t)$ are both od (D) $x_R(t)$ and $x_I(t)$ are both even	d en
MCQ 1.1.24	A signal $x(t)$ has energy $E_x$ , then energy (A) $E_x/ a ^2$ (C) $E_x a ^2$	y of the signal $x(at)$ is given by (B) $E_x/ a $ (D) $ a E_x$	
MCQ 1.1.25	The value of $\int_{0}^{\pi} 2\cos\omega t\delta(\omega)d\omega$ is		
	(A) 0 (C) 1	<ul> <li>(B) π/2</li> <li>(D) 2</li> </ul>	
MCQ 1.1.26	If $\delta(t)$ is the unit impulse function, then	$\int_{-\infty}^{\infty} x(t) \delta(t) dt$ equals to	
	(A) $x(t)$ (C) $x(\infty)$	<ul> <li>(B) x(0)</li> <li>(D) x(1)</li> </ul>	
MCQ 1.1.27	For unit impulse function $\delta(t)$ , which of (A) $\delta(-t) = \delta(\frac{t}{2})$	the following relation holds true (B) $\delta(-t) = \delta(t^2)$	?
	(C) $\delta(-t) = \delta(t)$	(D) $\delta(-t) = \delta^2(t)$	
MCQ 1.1.28	The function $f(t) = t\delta(t)$ will be equal to (A) $t$ (C) 1	$(B) \infty$	
MCQ 1-1-29	The unit impulse is defined as		
	(A) $\delta(t) = \infty, t = 0$	(B) $\delta(t) = \begin{cases} \infty, & t = 0 \\ 0, & t \neq 0 \end{cases}$	
	(C) $\delta(t) = \infty, t = 0$ and $\int_{-\infty}^{+\infty} \delta(t) dt = 0$	(D) $\delta(t) = \begin{cases} \infty, t = 0 \\ 0, t \neq 0 \end{cases}$ and $\int_{-\infty}^{+\infty} \delta(t) dt = 0$	t) $dt = 1$
MCQ 1.1.30	If $x(t)$ is a continuous time signal and $\delta$ integral $\int_{-\infty}^{\infty} x(t) \delta(t-t_0)$ is equal to	$\delta(t)$ is a unit impulse signal then	n value of
	(A) $x(t)$ (C) $\delta(t)$	(B) <b>x</b> (t <sub>0</sub> ) (D) 1	
MCQ 1.1.31	A weighted impulse function $\delta(at)$ has (A) unit area and unit amplitude (C) finite area and infinite amplitude	<ul><li>(B) infinite area and finite amp</li><li>(D) infinite area and infinite and</li></ul>	litude nplitude

- **MCQ 1.1.32** Unit step signal u(t) is
  - (A) an energy signal
  - (B) a power signal
  - (C) neither power signal nor energy signal
  - (D) both
- **MCQ 1.1.33** A unit step function is given by
  - (A)  $u(t) = \begin{cases} 1, & t \ge 0\\ 0, & t < 0 \end{cases}$  (B)  $u(t) = \begin{cases} 1, & t = 0\\ 0, & t \ne 0 \end{cases}$ (C)  $u(t) = \begin{cases} t, & t \ge 0\\ 0, & t < 0 \end{cases}$  (D)  $u(t) = \begin{cases} 1, & t > 0\\ 0, & t < 0 \end{cases}$
- **MCQ 1.1.34** Match List I with List II and choose the correct answer using the codes given below the lists :

#### List I (Signal)

- **P.** Unit Impulse signal
- Q. Unit Step signal
- **R.** Random noise signal

S. Decaying exponential Codes :

	Р	$\mathbf{Q}$	$\mathbf{R}$	$\mathbf{S}$
(A)	3	2	4	1
(B)	2	4	1	3
(C)	1	2	3	4
(D)	2	1	4	3

#### List II (Nature)

- 1. Sample values are unpredictable
- 2. Has only one non-zero value
- **3.** Amplitude decreases as time increases
- 4. Has only two possible values

**MCQ 1.1.35** A unit ramp function is defined as

1. 00

**m**1

----

(A) 
$$r(t) = \begin{cases} 1, & t = 0 \\ 0, & t \neq 0 \end{cases}$$
 (B)  $r(t) = \begin{cases} |t| + 1, & t \ge 0 \\ 0, & t < 0 \end{cases}$   
(C)  $r(t) = \begin{cases} t, & t \ge 0 \\ 0, & t < 0 \end{cases}$  (D)  $r(t) = \begin{cases} 1, & t \ge 0 \\ 0, & t < 0 \end{cases}$ 

1.

**MCQ 1.1.37** In terms of unit-step function, signum function is given as  
(A) 
$$\operatorname{sgn}(t) = -u(t)$$
 (B)  $\operatorname{sgn}(t) = 2u(t)$   
(C)  $2\operatorname{sgn}(t) = u(t)$  (D)  $\operatorname{sgn}(t) = 2u(t) - 1$ 







\*\*\*\*\*\*\*

#### Page 8

# **EXCERCISE 1.2**

MCQ 1.2.1	What is the period of a signal $x(t) = 3$	$\sin\left(4\pi t\right) + 7\cos\left(3\pi t\right) ?$
	(A) $2 \sec$	$(B) 4 \sec$
	(C) 12 sec	(D) $x(t)$ is not periodic
MCQ 1.2.2	The period of a signal $x(t) = 3\sin(4\pi t)$	$+7\cos(10t)$ is
	(A) $10\pi \sec$	(B) $5 \sec$
	(C) 6 sec	(D) $x(t)$ is not periodic
MCQ 1.2.3	Consider the following continuous time $x_1(t) = 6\sin(8\pi t) + 14\cos(6\pi t)$ $x_2(t) = 6\sin(8\pi t) + 14\cos(20t)$ Which of the following statement regar (A) $\pi(t)$ is periodic, $\pi(t)$ is appriadic.	signals ding the periodicity of the signals is true ?
	(A) $x_1(t)$ is periodic, $x_2(t)$ is aperiodic (D) $\mathbf{P}(t) = 1 \cdot 1 \cdot 1$	
	(B) Both $x_1(t)$ and $x_2(t)$ are periodic	
	(C) $x_1(t)$ is aperiodic, $x_2(t)$ is periodic	
	(D) Both $x_1(t)$ and $x_2(t)$ are aperiodic	
MCQ 1.2.4	What is the period of the signal $x(t) =$	$\sin\left(\frac{2\pi}{5}t\right)\cos\left(\frac{4\pi}{3}t\right)?$
	(A) 13 sec	(B) 91 sec
	(C) 15 sec	(D) $x(t)$ is aperiodic
MCQ 1.2.5	Match List I (Signal) with List II (Perio the codes given below	d of the signal) and select the answer using
	List I (Signals)	List II (Period of the signal)
	$\mathbf{P.}  f_1(t) = \sin\left(\frac{2\pi}{3}\right)t$	<b>1.</b> 15 Unit
	<b>Q.</b> $f_2(t) = \sin\left(\frac{2\pi}{5}t\right)\cos\left(\frac{4\pi}{3}t\right)$	2. 3 Unit
	<b>R.</b> $f_3(t) = \sin 3t$	<b>3.</b> aperiodic
	<b>S.</b> $f_4(t) = f_1(t) - 2f_3(t)$	4. $2\pi/3$ unit

	Code	s :					
		Р	Q	R	$\mathbf{S}$		
	(A)	1	4	3	2		
	(B)	3	2	1	4		
	(C)	1	2	3	4		
	(D)	2	1	4	3		
MCQ 1.2.6	Whic	h of th	e follov	ving sig	gnal is not per	odic?	
	(A) s	in(10t)				(B) $2\cos(5\pi t)$	
	(C) s	$in(10\pi)$	t) u(t)			(D) none of the	ese
MCQ 1.2.7	The p	period o	of the s	signal g	$g(t) = 2\cos(10$	$t+1) + \sin\left(4t - \right)$	1) is equal to
	(A) 1	$0  \sec$				(B) $\pi$ sec	
	(C) 2	sec				(D) $5 \sec$	
MCQ 1.2.8	Consi Which $(A) x$	der the h signa $_{3}(t)$ on	e signa ls is/a ly	ls $x_1(t)$ re aper	$= 5\cos\left(4t + \frac{\pi}{3}\right)$	), $x_2(t) = e^{j(\pi t - 1)}$ (B) $x_2(t)$ and $x_2(t)$	and $x_3(t) = [\cos(2t - \frac{\pi}{3})]^2$ $x_3(t)$
	(C) $x$	$t_2(t)$ on	ly			(D) none of ab	ove
MCQ 1.2.9	Consi	der a s	ignal $g$	$g(t) \det$	fined as $g(t) =$	$\begin{cases} t, & 0 \le t < 1 \\ 0, & \text{elsewhere} \end{cases}$	The odd part of $g(t)$ is
	(A) ·		$g_o(t)$		t	(B) $-\frac{1}{2}$	$p_o(t)$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$



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A signal g(t) is defined as MCQ 1.2.10  $g(t) = \begin{cases} t, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$ 

The even part of the signal g(t) is

(A) 
$$g_e(t) = \begin{cases} t/2, & -1 \le t < 0\\ t/2, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$$
 (B)  $g_e(t) = \begin{cases} -t/2, & -1 \le t < 0\\ t/2, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$ 

(C) 
$$g_e(t) = \begin{cases} -2t, & -1 \le t < 0\\ 2t, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$$
 (D)  $g_e(t) = \begin{cases} 2t, & -1 \le t < 0\\ 2t, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$ 

**MCQ 1.2.11** A CT signal is defined as
$$x(t) = \begin{cases} 2, & t > 0 \\ 0, & t < 0 \end{cases}$$
The odd part of  $x(t)$  is an unit

The odd part of x(t) is an unit

(A) step function

(A)

(C)

(C) impulse function

(B) signum function (D) ramp function

-1/2

0

1/2

The odd part of a unit step signal is MCQ 1.2.12



0

-1/2



**MCQ 1.2.13** A signal x(t) is shown in figure below



The odd part of the signal  $g(t) = x(t - \frac{3}{4}) + x(t + \frac{3}{4})$  will be



**MCQ 1.2.14** If  $x_e(t)$  and  $x_o(t)$  are the even and odd part of a signal x(t), then which of the following is true?

(A) 
$$x_o(0) = 0$$
 (B)  $x_e(0) = x(0)$   
(C)  $x_o(0) = x_e(0) = 0$  (D) Both (A) and (B)

#### Statement For Q. 15 & 16:

The figure shows parts of a signal x(t) and its odd part  $x_o(t)$ , for  $t \ge 0$  only, that is x(t) and  $x_o(t)$  are not given for t < 0.



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#### **MCQ 1.2.16** The complete even part $x_e(t)$ of the signal x(t) is



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**MCQ 1.2.17** A signal x(t) is shown in figure below



The odd part of signal x(t) is







Which of the following statement is true ?

- (A)  $g_1(t)$  is a power signal,  $g_2(t)$  is an energy signal.
- (B)  $g_1(t)$  is an energy signal,  $g_2(t)$  is a power signal.
- (C) Both  $g_1(t)$  and  $g_2(t)$  are power signals.
- (D) Both  $g_1(t)$  and  $g_2(t)$  are energy signals.

**MCQ 1.2.19** The average power  $(P_g)$  and energy  $(E_g)$  of the signal g(t) shown in figure are











**MCQ 1.2.22** The power and rms value of a voltage signal  $x(t) = 20\cos(5t)\cos(10t)$  V are respectively:

(A) $200 \text{ W}, 14.14 \text{ volt}$	(B) $100 \text{ W}, 7.07 \text{ volt}$
(C) 100 W, 10 volt	(D) 200 W, 10 volt

**MCQ 1.2.23** The signal  $x(t) = e^{j(2t + \frac{\pi}{4})}$  is (A) a power signal (B) an energy signal (C) neither a power nor an energy (D) none of above







	List I	(Sign	ual)			List II	(Energy)
Р.	2x(t)				1.	48 unit	
Q.	x(3t)				2.	12 unit	
R.	x(t-4)	)			3.	4 unit	
s.	2x(2t)				4.	24 unit	
Cod	es:						
	Р	Q	R	$\mathbf{S}$			

	Р	$\mathbf{Q}$	R	$\mathbf{S}$
$(\mathbf{A})$	1	3	2	4
(B)	4	3	1	2
(C)	1	4	3	2
(D)	4	1	2	3

MCQ 1.2.26

Consider the following statements regarding a signal  $x(t) = e^{-|t|}$ .

1. x(t) is an energy signal

2. x(t) is an odd signal

- 3. x(t) is an even signal
- 4. x(t) is neither even nor odd.

Which of the above statement is/are true?

(A) only 4 (B) 1 and 3

(C) 1 and 4 (D) 1 and 2

**MCQ 1.2.27** Consider the signals  $x_1(t)$ ,  $x_2(t)$  and y(t) as shown in below :



Which of the following relation is true ?

(A) 
$$y(t) = x_1(t) x_2(t)$$
  
(B)  $y(t) = x_1(t) + x_2(t)$   
(C)  $y(t) = x_1(t) - x_2(t)$   
(D) none of above





The plot for a signal x(t) = f(t) g(t-1) will be





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**MCQ 1.2.29** A continuous time signal is given as

$$g(t) = \begin{cases} t+1, & -1 \le t \le 0\\ 1, & 0 \le t < 2\\ 0, & \text{elsewhere} \end{cases}$$

The correct expression for g(2t) is

$$(A) \ g(2t) = \begin{cases} \frac{t}{2} + 1, & -0.5 \le t \le 0\\ t, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases} (B) \ g(2t) = \begin{cases} 2t + 1, & -0.5 \le t \le 0\\ 2, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$$

$$(C) \ g(2t) = \begin{cases} t + 1, & -0.5 \le t \le 0\\ 1, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases} (D) \ g(2t) = \begin{cases} 2t + 1, & -0.5 \le t \le 0\\ 2, & 0 \le t < 1\\ 0, & \text{elsewhere} \end{cases}$$

**MCQ 1.2.30** Consider a signal g(t) defined as following

$$g(t) = \begin{cases} t+1, & -1 \le t \le 0\\ 1, & 0 \le t \le 2\\ -t+3, & 2 \le t \le 3\\ 0, & \text{elsewhere} \end{cases}$$

The waveform of signal g(t/2) is









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#### Continuous Time Signals

Which of the following is the correct expression of f(t)? (A) f(t) = g(t) + g(t+2) + g(t+3)(B) f(t) = g(t) + g(t-2) + g(t-3)(C) f(t) = g(t) + g(t/2) + g(t/3)(D) f(t) = g(t) + g(2t) + g(3t)

**MCQ 1.2.32** Consider a unit triangular function  $\Delta(t)$  and a unit rectangular function  $\Pi(t)$  as shown in figure



Which of the following waveform is correct for  $g(t) = 3\Delta(2t/3) + 3\Pi(t/3)$ 







0

 $\frac{3}{2}$ 

 $\frac{3}{2}$ 

**MCQ 1.2.33** Time compression of a signal

(A) Reduces its energy

- (B) increases its energy
- (C) does not effect the energy
- (D) none of above.

MCQ 1.2.34 A CT signal is shown below



The plot of signal g(t+2) is



**MCQ 1.2.35** Consider the signal x(t) and y(t) shown is figures



Which of the following is correct statement ?

- (A) y(t) is amplitude scaled version of x(t)
- (B) y(t) is time scaled version of x(t) by a factor of 2.
- (C) y(t) is time advanced version of x(t) by 2 units.
- (D) y(t) is time delayed version of x(t) by 2 units.

**MCQ 1.2.36** The plot of a signal x(t) is shown in figure



If x(t) is delayed by 3 sec, then plot will be



#### Statement For Q. 37 & 38

Consider the signal g(t) as shown in figure







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<b>MCQ 1.2.38</b> Plot for signal $q(-t+1)$ wi	ill be
--	--------



If the energy of a signal x(t) is  $E_x$  then what will be the energy for a signal MCQ 1.2.39 x(at-b)?





Consider a signal f(t) as shown is figure



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2

1

0

► t







If plot of a signal f(t) is shown in figure below MCQ 1.2.41



Then the plot of signal f(-t-3) will be



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**MCQ 1.2.42** A signal x(t) and its transformed signal y(t) are shown in figure(A) and figure(B) respectively



If y(t) = x(at + b), then values of a and b are respectively (A) 3, -2 (B) -3, 6 (C) 3, -6 (D) -2, 3





Which of the following procedure is correct to obtain  $x_2(t)$  from  $x_1(t)$ ? (A) First compress  $x_1(t)$  by a factor of 3, then shift to the right by 6 time units. (B) First expand  $x_1(t)$  by a factor of 6, then shift to the right by 3 time units. (C) First compress  $x_1(t)$  by a factor of 3, then shift to the right by 2 time units. (D) First shift  $x_1(t)$  to the right by 2 time units then expand by a factor of 3.

#### Statement For Q. 44 & 45

The plot of a signal x(t) is shown in figure





**MCQ 1.2.45** Plot for the signal  $x_2(t) = x(-0.5t - 1)$  will be



Statement For Q. 46 & 47

Consider two CT signal x(t) and y(t) shown in figure below



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 MCQ 1.2.46
 Which of the following relation is true ?

 (A) y(t) = x(2t-8) (B) y(t) = x(2t-4) 

 (C)  $y(t) = x(\frac{t}{2}-2)$  (D)  $y(t) = x(\frac{t}{2}-4)$ 

**MCQ 1.2.47** The sketch of signal x(2-t) will be



**MCQ 1.2.48** Consider two signals x(t) and y(t) shown in figure below 1.4





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**MCQ 1.2.49** A signal x(t) is shown in the following figure



The plot for a transformed signal  $y(t) = -6x\left(\frac{t-1}{2}\right)$  will be







(D) None of above

**MCQ 1.2.50** A signal x(t) is transformed into another signal y(t) given as  $y(t) = x\left(1 - \frac{t}{2}\right)$ 



The waveform of the original signal x(t) is



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**MCQ 1.2.51** If  $\delta(t)$  is an unit impulse function, then the value of integral  $\int_{-\infty}^{\infty} e^{-t} \delta(2t-2) dt$  equals to



**MCQ 1.2.52** For an unit impulse function  $\delta(t)$ , which of the following is true? (A)  $\delta[a(t-t_0)] = \frac{1}{|a|} \delta(t)$  (B)  $\delta[a(t-t_0)] = |a| \delta(t-t_0)$ (C)  $\delta[a(t-t_0)] = \frac{1}{|a|} \delta(t-t_0)$  (D)  $\delta[a(t-t_0)] = |a| \delta(t)$ 

**MCQ 1.2.53** If  $\delta(t)$  is an unit impulse function then which of the following waveform represents a signal  $g(t) = 6\delta(3t+9)$ ?





(A) 1  
(C) 0  

$$x(t) = \int_{-\infty}^{\infty} \delta(t+5) \cos(\pi t) dt$$
  
(B) -1  
(D) 5

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**MCQ 1.2.55** If r(t) is a unit ramp function, then plot for signal r(-t+2) will be





**MCQ 1.2.57** For a signal x(t) = u(t+2) - 2u(t) + u(t-2) the waveform is



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Continuous Time Signals





The correct waveform of x(t) is



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### **EXCERCISE 1.3**

MCQ 1.3.1	The period of signal $x(t) = 14 + 50\cos 60t$ is	
	(A) $\frac{\pi}{30}$ sec	(B) $60\pi$ sec
	(C) $\frac{1}{60\pi}$ sec	(D) Not periodic
MCQ 1.3.2	<b>1.3.2</b> The period of signal $x(t) = 10 \sin 5t - 4 \cos 7t$ is	
	(A) $\frac{24\pi}{35}$	(B) $\frac{4\pi}{35}$
	(C) $2\pi$	(D) Not periodic
MCQ 1.3.3	The period of signal $x(t) = 5t - 2\cos 5000\pi t$ is	
	(A) 0.96 ms	(B) 1.4 ms
	(C) 0.4 ms	(D) Not periodic
MCQ 1.3.4	4 The period of signal $x(t) = 4\sin 3t + 3\sin \sqrt{t}$ is	
	(A) $\frac{2\pi}{3}$ sec	(B) $\frac{2\pi}{2\pi}$ sec

(A)  $\frac{2\pi}{3}$  sec (B)  $\frac{2\pi}{\sqrt{3}}$  sec (C)  $2\pi$  sec (D) Not periodic

### Statement for Q. 5 & 6

Consider the signal shown below



#### **MCQ 1.3.5** The even part of signal is



-1





#### **MCQ 1.3.6** The odd part of signal is









**3.7** Consider the function x(t) shown in figure



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The even part of x(t) is







**MCQ 1.3.8** The signal 
$$x(t) = e^{-4t}u(t)$$
 is a  
(A) power signal with power  $P_x = 1/4$  (B) power signal with power  $P_x = 0$   
(C) energy signal with energy  $E_x = 1/4$  (D) energy signal with energy  $E_x = 0$ 

MCQ 1.3.9The signal 
$$x(t) = e^{j(2t+\frac{\pi}{4})}$$
 is a  
(A) power signal with  $P_x = 1$   
(C) energy signal with  $E_x = 2$ (B) power signal with  $P_x = 2$   
(D) energy signal with  $E_x = 1$ 

**MCQ 1.3.10** The raised cosine pulse x(t) is defined as

$$x(t) = \begin{cases} \frac{1}{2}(\cos\omega t + 1), & -\frac{\pi}{\omega} \le t \le \frac{\pi}{\omega}\\ 0, & \text{otherwise} \end{cases}$$

The total energy of x(t) is

(A) 
$$\frac{3\pi}{4\omega}$$
 (B)  $\frac{3\pi}{8\omega}$   
(C)  $\frac{3\pi}{\omega}$  (D)  $\frac{3\pi}{2\omega}$ 

#### Statement for Q. 11 -14 :

Consider the six signals shown in figure below.



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5x(2t-1)

#### Statement for Q. 15-19:

The signal x(t) is depicted in figure below :



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Chapter 1

**MCQ 1.3.15** The trapezoidal pulse y(t) is related to the x(t) as y(t) = x(10t-5). The sketch of y(t) is



**MCQ 1.3.16** The trapezoidal pulse x(t) is time scaled producing y(t) = x(5t). The sketch for y(t) is







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**MCQ 1.3.18** The trapezoidal pulse x(t) is applied to a differentiator, defined by  $y(t) = \frac{dx(t)}{dt}$ . The total energy of y(t) is

(A) 0	(B) 1
(C) 2	(D) 3

MCQ 1.3.19	The total energy of $x(t)$ is		
	(A) 0	(B) 13	
	(C) 13/3	(D) $26/3$	

**MCQ 1.3.20** Consider the two signal shown in figure below.



The signal y(t) can be represented as

(A) 
$$2x(\frac{1}{2}t+2)+2$$
 (B)  $2x(2t-2)-2$   
(C)  $-2x(-2t+2)+2$  (D)  $-2x(-\frac{1}{2}t+4)+2$ 

**MCQ 1.3.21** The numerical value of integral  $\int_{-1}^{8} [\delta(t+3) - 2\delta(4t)] dt$  is

(A) 
$$-\frac{1}{2}$$
 (B)  $\frac{1}{2}$ 

(C) 2 (D) -2

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Chapter 1

MCQ 1.3.22

MCQ 1.3.23



**MCQ 1.3.24** The value of the function  $\int_{-\infty}^{\infty} \delta(at-b)\sin^2(t-4) dt$  where a > 0, is

(A) 1 (B) 
$$\frac{\sin^2(\frac{a}{b}-4)}{b}$$

**MCQ 1.3.25** Consider the function  $x(t) = u(t + \frac{1}{2}) \operatorname{ramp}(\frac{1}{2} - t)$ . The graph of x(t) is



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#### **MCQ 1.3.26** Consider the signal x(t) = rect(t) tri(t). The graph of x(t) is



# MCQ 1.3.27 A signal is defined as $x(t) = 4 \operatorname{tri}(t)$ . The value of $x(\frac{1}{2})$ is (A) 1/2 (B) 1 (C) 2 (D) 0

**MCQ 1.3.28** Consider the signal  $x(t) = 3\text{tri}\left(\frac{2t}{3}\right) + 3\text{rect}\left(\frac{t}{3}\right)$ . The graph of x(t) is



### Statement for Q. 29 - 30 :

Let the CT unit impulse function be defined by

$$\delta(x) = \lim_{\alpha \to 0} \left(\frac{1}{\alpha}\right) \operatorname{tri}\left(\frac{x}{\alpha}\right), \ a > 0$$

The function  $\delta(x)$  has an area of one regardless the value of  $\alpha$ 

What is the area of the function $\delta(4x)$ ?	
(A) 1	(B) $\frac{1}{4}$
(C) 4	(D) 2
What is the area of the function $\delta(-6x)$ (A) 1	)? (B)1/6
(C) 4	(D) 2
A signal $x(t)$ is defined as $x(t) = 2 \operatorname{tri} \left[ 2(t-1) \right] + 6 \operatorname{rect} \left( \frac{t}{4} \right)$ . The value of $x(\frac{3}{2})$ is	
(A) 4	(B) 5
(C) 6	(D) 7
	What is the area of the function $\delta(4x)$ ? (A) 1 (C) 4 What is the area of the function $\delta(-6x)$ (A) 1 (C) 4 A signal $x(t)$ is defined as $x(t) = 2\text{tri}[2(x)]$ (A) 4 (C) 6

**MCQ 1.3.32** A function is defined as x(t) = 1 + sgn(4 - t). The graph of x(t) is









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The function that describe the pulse are (A) 1 and 2 (B) 2 and 3

- (C) 1 and 3 (D) all
- **MCQ 1.3.35** A signal is described by x(t) = r(t-4) r(t-6), where r(t) is a ramp function starting at t = 0. The signal x(t) is represented as



#### **MCQ 1.3.36** For the waveform shown in figure the equation is



- (C) 3(1-t)u(t) + 1.5tu(t-1) + 1.5(t-2)u(t-3)
- (D) None of these

**MCQ 1.3.37** For the signal x(t) = u(t+1) - 2u(t-1) + u(t-3), the correct wave form is







**MCQ 1.3.39** For the signal x(t) = 2(t-1)u(t-1) - 2(t-2)u(t-2) + 2(t-3)u(t-3) the correct waveform is



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**MCQ 1.3.40** For the signal x(t) = (t+1)u(t-1) - tu(t) - u(t-2) the correct waveform is



#### **MCQ 1.3.41** Consider the two signal shown in figure



The signal y(t) can be explained as

(A)  $x(\frac{1}{2}t-1) + x(\frac{2}{3}t-\frac{5}{3}) + x(t-3) + x(2t-7)$ (B)  $x(2t+1) + x(\frac{3}{2}t+\frac{5}{3}) + x(t+3) + x(2t+7)$ (C)  $x(\frac{1}{2}t+1) + x(\frac{2}{3}t+\frac{5}{3}) + (t+3) + x(2t+7)$ (D)  $x(2t-1) + x(\frac{3}{2}t-\frac{5}{3}) + x(t-3) + x(2t-7)$ 

### Statement for Q. 42-43 :

Consider the triangular pulses and the triangular wave of figure



MCQ 1.3.42	The mathematical function for $x_1(t)$ is	
	(A) $2tu(t) - 4(t+1)u(t-1) + 2(t+2)u(t-2)$	
	(B) $2tu(t) - 4(t-1)u(t-1) + 2(t-2)u(t-2)$	
	(C) $2tu(t) - 4(t-1)u(t+1) + 2(t-2)u(t+2)$	
	(D) None of the above	

**MCQ 1.3.43** The mathematical function for waveform x(t) is

(A) 
$$\sum_{k=0}^{\infty} x_1(t+2k)$$
 (B)  $\sum_{k=-\infty}^{\infty} x_1(t-2k)$   
(C)  $\sum_{k=0}^{\infty} x_1(t-2k)$  (D)  $\sum_{k=-\infty}^{\infty} x_1(t+2k)$ 

Here,  $T_0 = 2$ , therefore

$$x(t) = \sum_{k=-\infty}^{\infty} x_1(t-2k)$$

\*\*\*\*\*\*\*\*

## **EXCERCISE 1.4**

MCQ 1.4.1 IES EC 2009	A function of one or more variable which conveys information on the nature of physical phenomenon is called		
110 10 2007	(A) Noise	(B) Interference	
	(C) System	(D) Signal	
MCQ 1.4.2 GATE IN 2006	The Fourier series for a periodic signal is given as $x(t) = \cos(1.2\pi t) + \cos(2\pi t) + \cos(2.8\pi t)$		
	(A) $0.2 \text{ Hz}$	(B) 0.6 Hz	
	(C) 1.0 Hz	(D) 1.4 Hz	
<b>MCQ 1.4.3</b> GATE IN 2007	Consider the periodic signal $x(t) = (1 + 0.5 \cos 40\pi t) \cos 200\pi t$ , where t is in seconds. Its fundamental frequency in Hz is		
	(A) 20	(B) 40	
	(C) 100	(D) 200	
MCQ 1.4.4 GATE IN 2009	The fundamental period of $x(t) = 2\sin 2t$ is	$\pi t + 3\sin 3\pi t$ , with t expressed in seconds,	
	(A) 1 s	(B) 0.67 s	
	(C) 2 s	(D) 3 s	
MCQ 1.4.5	The period of the function $\cos[\pi/4(t-1)]$ is		
IES EC 1999	(A) $1/8 \text{ s}$	(B) 8 s	
	(C) 4 s	(D) 1/4 s	
MCQ 1.4.6 IES EC 2001	If $x_1(t) = 2 \sin \pi t + \cos 4\pi t$ and $x_2(t) = \sin 5\pi t + 3 \sin 13\pi t$ , then (A) $x_1$ and $x_2$ both are periodic (B) $x_1$ and $x_2$ both are not periodic (C) $x_1$ is periodic, but $x_2$ is not periodic (D) $x_1$ is not periodic, but $x_2$ is periodic		
MCQ 1.4.7 IES EC 2003	<ul><li>The sum of two or more arbitrary sinusc</li><li>(A) Always periodic</li><li>(B) Periodic under certain conditions</li></ul>	oids is	

	<ul><li>(C) Never periodic</li><li>(D) Periodic only if all the sinusoids are</li></ul>	identical in frequency and phase	
MCQ 1.4.8 IES EC 2004	Which one of the following must be satisfied if a signal is to be periodic for $\infty < t < \infty$ ?		
	(A) $x(t + T_0) = x(t)$	(B) $x(t + T_0) = dx(t) / dt$	
	(C) $x(t + T_0) = \int_t^{T_0} x(t) dt$	(D) $x(t + T_0) = x(t) + kT_0$	
MCQ 1.4.9 IES EC 2007	Consider two signals $x_1(t) = e^{j20t}$ and $x_2(t) = e^{(-2+j)t}$ . Which one of the following statements is correct? (A) Both $x_1(t)$ and $x_2(t)$ are periodic (B) $x_1(t)$ is periodic but $x_2(t)$ is not periodic (C) $x_2(t)$ is periodic but $x_1(t)$ is not periodic (D) Neither $x_1(t)$ nor $x_2(t)$ is periodic		
MCQ 1.4.10	Which one of the following function is a periodic one ?		
IES EC 2008	(A) $\sin(10\pi t) + \sin(20\pi t)$	$(B) \sin(10t) + \sin(20\pi t)$	
	$(C) \sin(10\pi t) + \sin(20t)$	(D) $\sin(10t) + \sin(25\pi t)$	
MCQ 1.4.11	The period of the signal $x(t) = 8\sin\left(0.8\pi t + \frac{\pi}{4}\right)$ is		
GALE EE 2010	(A) $0.4\pi$ s	(B) $0.8\pi$ s	
	(C) 1.25 s	(D) 2.5 s	
MCQ 1.4.12 IES EC 2009	A signal $x_1(t)$ and $x_2(t)$ constitute the real and imaginary parts respectively of a complex valued signal $x(t)$ . What form of waveform does $x(t)$ possess ? (A) Real symmetric (B) Complex symmetric (C) Asymmetric (D) Conjugate symmetric		
MCQ 1.4.13	If from the function $f(t)$ one forms the function $f(t)$ even	unction, $\Psi(t) = f(t) + f(-t)$ , then $\Psi(t)$ is (B) odd	
	(C) neither even nor odd	(D) both even and odd	
MCQ 1.4.14 IES EC 2001	The signal $x(t) = A\cos(\omega t + \phi)$ is (A) an energy signal (C) an energy as well as a power signal	<ul><li>(B) a power signal</li><li>(D) neither an energy nor a power signal</li></ul>	
MCQ 1.4.15 IES EC 2007	Which one of the following is the mat power of the signal $x(t)$ ? (A) $\frac{1}{2\pi} \int_{-\pi}^{T} x(t) dt$	Which one of the following is the mathematical representation for the average power of the signal $x(t)$ ?	
	(C) $\frac{1}{T} \int_{0}^{T/2} x(t) dt$	(D) $\lim_{t \to 0} \frac{1}{t} \int_{0}^{T/2} r^{2}(t) dt$	
	$T J_{-T/2} $	$T \xrightarrow{T} T \xrightarrow{T} \infty T \int_{-T/2} d (v) dv$	

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MCQ 1.4.16 IES EC 2007	Which one of the following is correct ?		
	(A) finite	(B) zero	
	(C) infinite	(D) between 1 and 2 $(D)$	
MCQ 1.4.17	The power in the signal	$s(t) = 8\cos(20\pi - \frac{\pi}{2}) + 4\sin(15\pi t)$ is	
GATE EC 2005	(A) 40	(B) 41	
	(C) 42	(D) 82	
MCQ 1.4.18	Which of the following is true ?		
GATE EE 2006	(A) A finite signal is always bounded		
	(B) A bounded signal always possesses finite energy		
	(C) A bounded signal is always zero outside the interval $[-t_0, t_0]$ for some $t_0$		
	(D) A bounded signal is always finite		
MCQ 1.4.19	If a signal $f(t)$ has energy E, the energy of the signal $f(2t)$ is equal to		
GATE EC 2001	(A) 1	(B) $E/2$	
	(C) $2E$	(D) $4E$	
MCQ 1.4.20	If a function $f(t) u(t)$ is shifted to right side by $t_0$ , then the function can be expressed		
IES EC 2001			
	(A) $f(t - t_0) u(t)$	(B) $f(t) u(t - t_0)$	
	(C) $f(t-t_0) u(t-t_0)$	(D) $f(t+t_0) u(t+t_0)$	
MCQ 1.4.21	If a plot of signal $x(t)$ is as shown in the figure		
IES EC 1999	x(t)		
	2		

then the plot of the signal x(1-t) will be

2

0

 $^{-1}$ 

1

-1

 $\frac{3}{\phantom{2}}$  t











$$v[n] = \begin{cases} 1 & ; n = 1 \\ -1 & ; n = -1 \\ 0 & ; n = 0 \text{ and } |n| > 1 \end{cases}$$

Which is the value of the composite signal defined as v[n] + v[-n]? (A) 0 for all integer values of n

- (B) 2 for all integer values of  $\boldsymbol{n}$
- (C) 1 for all integer values of n
- (D) -1 for all integer values of n

**MCQ 1.4.23** Which one of the following relations is not correct ?

(A) 
$$f(t)\delta(t) = f(0)\delta(t)$$
  
(B)  $\int_{-\infty}^{\infty} f(t)\delta(\tau) d\tau = 1$   
(C)  $\int_{-\infty}^{\infty} \delta(\tau) d\tau = 1$   
(D)  $f(t)\delta(t-\tau) = f(\tau)\delta(t-\tau)$ 

**MCQ 1.4.24** The Dirac delta function  $\delta(t)$  is defined as

GATE EC 2006 (A)  $\delta(t) = \begin{cases} 1 & t = 0 \\ 0 & \text{otherwise} \end{cases}$  (B)  $\delta(t) = \begin{cases} \infty & t = 0 \\ 0 & \text{otherwise} \end{cases}$ 

(C) 
$$\delta(t) = \begin{cases} 1 & t = 0 \\ 0 & \text{otherwise} \end{cases}$$
 and  $\int_{-\infty}^{\infty} \delta(t) dt = 1$   
(D)  $\delta(t) = \begin{cases} \infty & t = 0 \\ 0 & \text{otherwise} \end{cases}$  and  $\int_{-\infty}^{\infty} \delta(t) dt = 1$ 

**MCQ 1.4.25** Let  $\delta(t)$  denote the delta function. The value of the integral  $\int_{-\infty}^{\infty} \delta(t) \cos\left(\frac{3t}{2}\right) dt$  is (A) 1 (B) -1

(A) 1 (B) 
$$-1$$
  
(C) 0 (D)  $\frac{\pi}{2}$ 

**MCQ 1.4.26** The Integral  $\int_{-\infty}^{\infty} \delta\left(t - \frac{\pi}{6}\right) 6\sin(t) dt$  evaluates to GATE IN 2010

(C) 
$$1.5$$
 (D)  $0$ 

**MCQ 1.4.27** The integral  $\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} t^2 e^{-t^2/2} \delta(1-2t) dt$  is equal to GATE IN 2011

(A) 
$$\frac{1}{8\sqrt{2\pi}}e^{-1/8}$$
 (B)  $\frac{1}{4\sqrt{2\pi}}e^{-1/8}$   
(C)  $\frac{1}{\sqrt{2\pi}}e^{-1/2}$  (D) 1

**MCQ 1.4.28** Double integration of a unit step function would lead to (A) an impulse (B) a parabola

**MCQ 1.4.29** The function x(t) is shown in the figure. Even and odd parts of a unit step function **GATE EC 2005** u(t) are respectively,



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**MCQ 1.4.30** The expression for the wave form in terms of step function is given by v(t)







MCQ 1.4.32Match List I with List II and select the correct answer using the codes given belowIES E C 1997the Lists:



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MCQ 1.4.33 IES EC 2004 Chapter 1





Which one of the following gives the correct description of the waveform shown in the above diagram ?

(A) 
$$u(t) + u(t-1)$$
  
(B)  $u(t) + (t-1)u(t-1)$   
(C)  $u(t) + u(t-1) + (t-2)u(t-2)$   
(D)  $u(t) + (t-2)u(t-2)$ 

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MCQ 1.4.34Match the waveforms on the left-hand side with the correct mathematical descriptionGATE EE 1994listed on the right hand side.







\*\*\*\*\*\*\*

# **SOLUTIONS 1.1**

# **SOLUTIONS 1.2**

Option (A) is correct. SOL 1.2.1  $T_1 = \frac{2\pi}{4\pi} = \frac{1}{2}$ Period of  $\sin(4\pi t)$ ,  $T_2 = \frac{2\pi}{3\pi} = \frac{2}{3\pi}$ Period of  $\cos(3\pi t)$ ,  $\frac{T_1}{T_2} = \frac{1/2}{2/3} = \frac{3}{4}$  (rational) Ratio, So, the signal x(t) is periodic. Period of x(t),  $T = \text{LCM}(T_1, T_2) = \text{LCM}\left(\frac{1}{2}, \frac{2}{3}\right) = 2 \sec t$ **Alternate Method :**  $\frac{T_1}{T_2} = \frac{m}{n}$ Fundamental period of x(t) $T = nT_1 = mT_2$  $\frac{T_1}{T_2} = \frac{3}{4} = \frac{m}{n}$ Here m = 3, n = 4Thus  $T = nT_1 = 4 \times \frac{1}{2} = 2 \sec \theta$ Period of x(t),  $T = mT_2 = 3 \times \frac{2}{3} = 2 \sec$ or Option (D) is correct. SOL 1.2.2  $T_1 = \frac{2\pi}{4\pi} = \frac{1}{2}$ Period of  $\sin(4\pi t)$ ,  $T_2 = \frac{2\pi}{10} = \frac{\pi}{5}$ Period of  $\cos(10t)$ ,  $\frac{T_1}{T_2} = \frac{1/2}{\pi/5} = \frac{5}{2\pi}$  (not rational) Here Since the ratio  $T_1/T_2$  is not rational, x(t) is not periodic. Option (A) is correct. SOL 1.2.3 For  $x_1(t)$ : Period of  $\sin(8\pi t)$ ,  $T_1 = \frac{2\pi}{8\pi} = \frac{1}{4}$  $T_2 = \frac{2\pi}{6\pi} = \frac{1}{3}$ Period of  $\cos(6\pi t)$ ,

Now

Now 
$$\frac{T_1}{T_2} = \frac{1/4}{1/3} = \frac{3}{4}$$
 (rational)  
Ratio  $T_1/T_2$  is a rational number, therefore  $x_1(t)$  is a periodic signal.  
For  $x_2(t)$ :  
Period of  $\sin(8\pi t)$ ,  $T_1 = \frac{2\pi}{8\pi} = \frac{1}{4}$   
Period of  $\cos(20t)$ ,  $T_2 = \frac{2\pi}{20} = \frac{\pi}{10}$   
Check for periodicity  $\frac{T_1}{T_2} = \frac{1/4}{\pi/10} = \frac{5}{2\pi}$  (not rational)  
Ratio  $T_1/T_2$  is not rational, therefore  $x_2(t)$  is not periodic.  
Option (C) is correct.  
 $x(t) = \sin\left[\left(\frac{2\pi}{5}\right)t\right] \cos\left[\left(\frac{4\pi}{3}\right)t\right]$   $\sin A \cos B = \frac{1}{2}\left[\sin(A - B) + \sin(A + B)\right]$   
 $= \frac{1}{2}\left[\sin\left(\frac{-14\pi}{15}\right)t + \sin\left(\frac{26\pi}{15}\right)t\right]$   
 $= x_1(t) + x_2(t)$   
Period of  $x_1(t)$ ,  $T_1 = \frac{2\pi}{22}$   
 $\frac{2\pi}{(26\pi/15)} = \frac{15}{13}$   
 $\frac{T_1}{2} = \frac{15/13}{15/13} = \frac{13}{13} = \frac{m}{n}$  (rational)  
Here  $m = 13$  and  $n = 7$ . Let period of  $x(t)$  is  $T$ , then  
 $T = mT_2 = nT_1$   
Thus,  $T = 13 \times \frac{15}{13} = 15 \sec$   
or  $T = 7 \times \frac{15}{7} = 15 \sec$   
**Alternate Method**:  
Period of  $x(t)$ ,  $T_1 = LCM(T_1, T_2)$   
 $T = LCM\left(\frac{15}{17}, \frac{13}{13}\right)$   
 $= 15 \sec$   
Option (D) is correct  
Period of  $f_1(t)$ ,  $T_1 = \frac{2\pi}{2\pi/3} = 3 \min \frac{f_1(t)}{f_1(t)} + \sin\left(\frac{2\pi}{5} + \frac{4\pi}{3}\right)t\right]$   
 $= \frac{1}{4}\left[\sin\left(-\frac{14\pi}{5}\right)t + \sin\left(\frac{2\pi}{5}, \frac{4\pi}{3}\right)t\right]$   
 $= \frac{1}{4}\left[\sin\left(-\frac{14\pi}{5}\right)t + \sin\left(\frac{2\pi}{5}, \frac{4\pi}{3}\right)t\right]$   
 $= \frac{1}{4}\left[\sin\left(-\frac{14\pi}{5}\right)t + \sin\left(\frac{2\pi}{5}, \frac{4\pi}{3}\right)t\right]$ 

Let

SOL 1.2.4

SOL 1.2.5

	Period of $f_{21}(t)$ ,	$T_{21} = \frac{2\pi}{(14\pi/15)} = \frac{15}{7}$
	Period of $f_{22}(t)$ ,	$T_{22} = \frac{2\pi}{(26\pi/15)} = \frac{15}{13}$
	Ratio,	$\frac{T_{21}}{T_{22}} = \frac{15/7}{15/13} = \frac{13}{7}$ (rational)
	So, $f_2(t)$ is period	ic.
	Period of $f_2(t)$ ,	$T_2 = \text{LCM}(T_{21}, T_{22}) = \text{LCM}\left(\frac{15}{7}, \frac{15}{13}\right) = 15 \text{ sec}$
	Period of $f_3(t)$ ,	$T_3 = \frac{2\pi}{3}$ unit
	fa Ratio	$f_{1}(t) = f_{1}(t) - 2f_{3}(t)$ $rac{T_{1}}{T_{3}} = rac{3}{2\pi/3} = rac{9}{2\pi}$ (not rational)
	Therefore $f_1(t)$ is	aperiodic.
	Codes, $P =$	$2, Q \rightarrow 1, R \rightarrow 4, S \rightarrow 3$
SOL 1.2.6	Option (C) is correspondent to $(10\pi t) u$	rect (t) is not periodic as it is defined for $t > 0$ only.
SOL 1.2.7	Option (B) is corr	rect.
	Let, g	$g(t) = 2\cos(10t+1) + \sin(4t-1)$
	Period of $g_1(t)$ ,	$T_1 = \frac{2\pi}{10} = \frac{\pi}{5} \sec$
	Period of $g_2(t)$ ,	$T_2 = \frac{2\pi}{4} = \frac{\pi}{2} \sec$
	Ratio,	$\frac{T_1}{T_2} = \frac{\pi/5}{\pi/2} = \frac{2}{5}$ (rational)
	Therefore, $g(t)$ is	periodic
	Period of $g(t)$ ,	$T = \operatorname{LCM}(T_1, T_2) = \operatorname{LCM}\left(\frac{\pi}{5}, \frac{\pi}{2}\right) = \pi \operatorname{sec}$
SOL 1.2.8	Option (D) is corr	rect.
	All the given sign	als are periodic.
	Period of $x_1(t)$ ,	$T_1 = \frac{2\pi}{4} = \frac{\pi}{2}$
	Period of $x_2(t)$ ,	$T_2 = \frac{2\pi}{\pi} = 2$
	Period of $x_3(t)$ ,	$T_3 = \frac{2\pi}{4} = \frac{\pi}{2}$
	None of the above	e signals is aperiodic.
SOL 1.2.9	Option (C) is corr	rect.
	Odd part of $g(t)$ ,	
	$g_{c}$	$g_{0}(t) = \frac{1}{2}[g(t) - g(-t)]$

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$$g(-t) = \begin{cases} -t, & 0 \leq -t < 1\\ 0, & \text{elsewhere} \end{cases}$$
$$= \begin{cases} -t, & -1 < t \leq 0\\ 0, & \text{elsewhere} \end{cases}$$
So,
$$g_o(t) = \begin{cases} t/2, & -1 \leq t < 0\\ t/2, & 0 \leq t < 1\\ 0, & \text{elsewhere} \end{cases}$$

**SOL 1.2.10** Option (B) is correct.

$$g(-t) = \begin{cases} -t, & -1 \le t < 0\\ 0, & \text{elsewhere} \end{cases}$$

Even part

$$g_e(t) = \frac{1}{2} [g(t) + g(-t)]$$
  
= 
$$\begin{cases} -t/2, & -1 \le t < 0 \\ t/2, & 0 \le t < 1 \\ 0, & \text{elsewhere} \end{cases}$$

Graphically :



**SOL 1.2.11** Option (B) is correct.  
Odd part of 
$$x(t)$$
,  $x_o(t) = \frac{1}{2}[x(t) - x(-t)]$ 

This is shown graphically as below :



Sample Chapter GATE CLOUD Signals & System by Kanodia The function  $x_o(t)$  is unit signum function.

**SOL 1.2.12** Option (B) is correct.

Odd

Unit step signal is given as

$$\begin{aligned} x(t) &= \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases} \\ x_o(t) &= \frac{1}{2} [x(t) - x(-t)] \end{aligned}$$

This is shown graphically as below :





Shift x(t) 3/4 units to the left and 3/4 units to the right and then adding both together, we get g(t) as shown below :



The signal g(t) is symmetrical with respect to vertical axis so odd part  $g_o(t) = 0$ 

**SOL 1.2.14** Option (D) is correct. For an odd signal

$$egin{aligned} & x_o(-t) = - x_o(t) \ & x_o(t) = - x_o(-t) \ & x_o(0) = - x_o(-0) \end{aligned}$$

The only number with a = -a is a = 0 so  $x_o(0) = 0$ For a signal we write

For 
$$t = 0$$
,  $x(t) = x_e(t) + x_o(t)$   
 $x(0) = x_e(0) + x_o(0)$   
 $= x_e(0) + 0 = x_e(0)$  Since  $x_o(0) = 0$ 

**SOL 1.2.15** Option (B) is correct. For any odd signal  $x_o(-t) = -x_o(t)$ . Thus the complete odd part is in option (B). **SOL 1.2.16** Option (D) is correct.

For any signal  $x(t) = x_e(t) + x_o(t)$ or  $x_e(t) = x(t) - x_o(t)$ 

Since we have x(t) and  $x_o(t)$  for  $t \ge 0$  only, from above equation we can plot  $x_e(t)$  for  $t \ge 0$  as shown below.



Even part of any signal is symmetric about vertical axis that is  $x_e(-t) = x_e(t)$ . Thus the complete even part is as shown above.

**SOL 1.2.17** Option (D) is correct.

Given signal is shown below :



By folding the signal with respect to vertical axis





which is shown below



Option (B) is correct. SOL 1.2.18 For signal  $g_1(t)$ 

Energ

Energy, 
$$E_1 = \int_{-\infty}^{\infty} |g_1(t)|^2 dt = \int_{-2}^{2} 25 dt = 100$$
  
Average Power, 
$$P_1 = \lim_{T \to \infty} \frac{1}{T} E_1 = 0$$

Since  $g_1(t)$  has finite energy, it is an energy signal. For signal  $g_2(t)$ 

Energy,

Energy, 
$$E_2 = \int_{-\infty}^{\infty} |g_2(t)|^2 dt = \infty$$
  
Average power,  $P_2 = \frac{1}{8} \int_{-4}^{4} |g_2(t)|^2 dt$   
 $= \frac{1}{8} \int_{-2}^{2} 25 dt = \frac{1}{8} \times 100 = 12.5$ 

The signal  $g_2(t)$  has finite power, so it is a power signal.

#### **Alternate Method :**

We know that most periodic signals are usually power signals and most non-periodic signals are considered to be energy signals.  $g_1(t)$  is non-periodic, so it is an energy signal.  $g_2(t)$  is periodic so it is a power signal.

Option (B) is correct. SOL 1.2.19

Energy,

$$E_g = \int_{-\infty}^{\infty} |g(t)|^2 dt = \int_{-3}^{3} 25 dt = 150$$
  
Power, 
$$P_g = \lim_{T \to \infty} \frac{1}{T} E_g = 0$$

Average P

Option (D) is correct. SOL 1.2.20

Energy,

$$E_x = \int\limits_{-\infty}^{\infty} |x(t)|^2 dt = \infty$$

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	Average Power, $P_x = \frac{1}{8} \int_{-4}^{4}  x(t) ^2 dt$
	$=\frac{1}{8}\int_{-2}^{2}25dt=\frac{100}{8}=12.5$
SOL 1.2.21	Option (D) is correct. The signal is unbounded, therefore it is not an energy signal.
SOL 1.2.22	Option (C) is correct.
	$x(t) = 20\cos(5t)\cos(10t) \mathrm{V}$
	$= 10 \left[ \cos 15t + \cos 5t \right] \qquad 2\cos A \cos B = \cos \left(A - B\right) + \cos \left(A + B\right)$
	$= 10\cos 15t + 10\cos 5t$
	Power $P_x = \frac{(10)^2}{2} + \frac{(10)^2}{2} = 100 \text{ W}$
	rms value $X_{rms} = \sqrt{100} = 10 \text{ volt}$
SOL 1.2.23	Option (A) is correct.
	Here $ x(t)  =  e_{\infty}^{j(2t+\pi/4)}  = 1$
	Energy of the signal $E_x = \int_{-\infty}  x(t) ^2 dt = \int_{-\infty} 1 dt = \infty$
	The power of signal, $P = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T}  x(t) ^2 dt$
	$= \lim_{T \to \infty} \frac{1}{2T} \int_{T}^{T} 1  dt = \lim_{T \to \infty} \frac{1}{2T} (2T) = 1$
	Since $x(t)$ has finite power and infinite energy, therefore it is a power signal.
SOL 1.2.24	Option (B) is correct.
	Power, $P_x = \frac{1}{T} \int_0^T  x(t) ^2 dt$ , $T \to \text{Period}$
	$-1\int_{-1}^{7} \int_{-1}^{7} dt$

$$= \frac{1}{7} \int_{0}^{7} |x(t)|^{2} dt$$

$$P_{x} = \frac{1}{7} \left[ \int_{0}^{2} (0)^{2} dt + \int_{2}^{5} (4)^{2} dt + \int_{5}^{7} (2)^{2} dt \right]$$

$$= \frac{1}{7} [0 + (16 \times 3) + (4 \times 2)]$$

= 8 unit

**SOL 1.2.25** Option (A) is correct.  
Energy 
$$E_x$$
 of signal  $x(t)$  is given as
$$E_x = \int_{-3}^{3} |x(t)|^2 dt = 12 \text{ units}$$

Energy of 2x(t),

$$E_1 = (2)^2 \times E_x = 4 \times 12 = 48$$
 unit

Let, 
$$x_2(t) = x(3t)$$
  
So,  $x_2(t)$  is defined over the range  $-1 \le t \le 1$   
Energy  $E_2 = \int_{-1}^{1} |x_2(t)|^2 dt = \int_{-1}^{1} |x(3t)|^2 dt$   
Let  $3t = \alpha \longrightarrow dt = \frac{1}{3} d\alpha$   
So  $E_2 = \frac{1}{3} \int_{-3}^{3} |x(\alpha)|^2 d\alpha = \frac{1}{3} \times E_x = 4$  unit

Energy of x(t-4) is same as x(t). Energy of 2x(2t)

$$E_4 = (2)^2 \times \frac{1}{2} E_x = 24$$
 unit

**SOL 1.2.26** Option (B) is correct.

$$egin{aligned} x(t) &= e^{-|t|}, \ x(-t) &= e^{-|t|} = e^{-|t|} = x(t) \end{aligned}$$

Since x(t) = x(-t), it is an even signal.

Signal x(t) is bounded, so it is has some finite energy.



**SOL 1.2.27** Option (A) is correct.

 $\begin{array}{l} y(t) \text{ is multiplication of } x_1(t) \text{ and } x_2(t). \\ \text{For interval } 0 \leq t \leq 1, \qquad x_1(t) = t, \ x_2(t) = 1 \\ \text{so,} \qquad y(t) = x_1(t) \ x_2(t) = t \\ \text{For } 1 \leq t \leq 2, \qquad x_1(t) = 1, \ x_2(t) = 0.5 \\ y(t) = x_1(t) \ x_2(t) = 0.5 \\ \text{For } 2 \leq t \leq 3, \qquad x_1(t) = 0.5, \ x_2(t) = 1.5 \\ y(t) = x_1(t) \ x_2(t) = 0.75 \end{array}$ 

**SOL 1.2.28** Option (C) is correct.

Shift g(t) to the right by one time unit to obtain g(t-1) as shown below :



For $-1 \leq t \leq 0$ ,	$f(t) = -t - 1, \ g(t - 1) = 1$
So,	x(t) = -t - 1
For $0 \leq t \leq 1$ ,	f(t) = t, g(t-1) = -1
So,	x(t) = -t
For $1 \leq t \leq 2$ ,	f(t) = 1, g(t-1) = t-2
So,	x(t) = t - 2
For $2 \le t \le 3$	f(t) = -t + 3, g(t - 1) = 1
So,	x(t) = -t + 3

**SOL 1.2.29** Option (D) is correct. Put  $t = 2\alpha$ ,

$$g(2\alpha) = \begin{cases} 2\alpha + 1, & -1 \le 2\alpha \le 0\\ 1, & 0 \le 2\alpha < 2\\ 0, & \text{else where} \end{cases}$$

Changing the variable  $(\alpha \rightarrow t)$ 

$$g(2t) = \begin{cases} 2t+1, & -\frac{1}{2} \le t \le 0\\ 1, & 0 \le t < 1\\ 0, & \text{else where} \end{cases}$$

SOL 1.2.30

Option (C) is correct.

The waveform for signal g(t) and g(t/2) are drawn as below.



Signal g(t/2) is obtained by expanding the g(t) by a factor of 2 in the time domain.

**SOL 1.2.31** Option (C) is correct. The signal g(t) and its expanded signal by factor of 2 and 3 is shown below :



By adding all three, we get

$$f(t) = g(t) + g(t/2) + g(t/3)$$

**SOL 1.2.32** Option (B) is correct.  $2\Lambda (2t/2)$  is obtained by av

 $3\Delta(2t/3)$  is obtained by expanding  $\Delta(t)$  with a factor of 3/2 and scaling amplitude by a factor of 3.



Similarly, to get  $3\Pi(t/3)$ , expand  $\Pi(t)$  by a factor of 3 and amplitude scale by 3



Now adding both signal we get



**SOL 1.2.33** Option (A) is correct. Energy of a signal x(t),  $E_x = \int_{-\infty}^{\infty} |x(t)|^2 t$ 

Now let the signal is time compressed by a factor of a

$$y(t) = x(at)$$
  
Energy of  $y(t)$   
$$E_y = \int_{-\infty}^{\infty} |x(at)|^2 dt$$
$$at = \alpha \Rightarrow dt = \frac{1}{a} d\alpha$$
$$E_y = \frac{1}{a} \int_{-\infty}^{\infty} |x(\alpha)|^2 d\alpha = \frac{1}{a} E_x$$

So due to time compression energy reduces.

- **SOL 1.2.34** Option (B) is correct. To get g(t+2) shift g(t) to the left by 2 time units. The signal is advanced by 2 time units.
- **SOL 1.2.35** Option (D) is correct.

The signal y(t) is the time delayed version of x(t) i.e. y(t) = x(t-2)

- **SOL 1.2.36** Option (A) is correct.
  - The delayed version of x(t),

$$y(t) = x(t-3)$$

can be obtained directly by shifting x(t) to the right by 3 sec.

**SOL 1.2.37** Option (C) is correct.

The time delayed signal g(t-2) can be obtained by shifting g(t) to the right by 2 time units.

**SOL 1.2.38** Option (C) is correct. First time reverse the signal g(t) to get g(-t) and then shift g(-t), toward right to get g(-t+1) as shown in figure



$$f(t) \xrightarrow{t \to -t} f(-t) \xrightarrow{t \to t-4} f(-t) \xrightarrow{t \to t-4} f(4-t) \xrightarrow{t \to 2t} f(4-2t)$$

This can be performed in following steps



Alternate Method : As given in methodology of section 1.4, we can also follow the other sequence of operation which is given as

$$f(t) \xrightarrow{t \to t+4} f(t+4) \xrightarrow{t \to 2t} f(2t+4) \xrightarrow{t \to -t} f(-2t+4)$$
**SOL 1.2.41** Option (C) is correct.

First we obtain time reversal signal f(-t) by taking mirror image of f(t) along the vertical axis. Then by shifting f(-t) to the left by 3 units we get f(-t-3).



**SOL 1.2.42** Option (C) is correct. We can see that y(2) = x(0) [origin is shifted at 2] so 2a + b = 0 ...(i) Similarly y(8/3) = x(2)So  $\frac{8}{3}a + b = 2$  ...(ii) From eq (i) and (ii) a = 3, b = -6

**SOL 1.2.43** Option (C) is correct.

From the graph we can write  $x_2(t) = x_1(3t-6) = x_1[3(t-2)]$ . So  $x_2(t)$ , can be obtained by compressing  $x_1(t)$  by a factor of 3 and then delaying by 2 time units.

### Alternate Method :

As given in methodology of section 1.4,  $x_2(t)$  can be obtained by shifting  $x_1(t)$  by 6 time units to the right and then by scaling(compressing) it with a factor of 3. This is not given in any of the four options.

**SOL 1.2.44** Option (B) is correct.

or

 $x_1(t) = x[0.5(t-2)]$  $x_1(t) = x(0.5t-1)$ 

First shift x(t) to right by one unit to get x(t-1). Then, expand x(t-1) by a factor of 2 to get  $x(\frac{t}{2}-1)$  or x(0.5t-1)



If we change sequence of transformation by first doing scaling then shifting we get

$$x(t) \xrightarrow{t \to 0.5t} x(0.5t) \xrightarrow{t \to t-1} x[0.5(t-1)] \neq x[0.5t-1]$$

Hence (B) is correct option.

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**SOL 1.2.45** Option (C) is correct.

 $x_2(t) = x(-0.5t-1)$ 

First shift x(t) to the right by 1 unit, we get x(t-1). Then, expand x(t-1) by a factor of 2 to get x(t/2-1)



Now fold signal x(0.5t-1) about the vertical axis to get x(-0.5t-1)



If we change the order of transformation we get

$$x(t) \xrightarrow{t \to 0.5t} x(0.5t) \xrightarrow{t \to t-1} x[0.5(t-1)] \xrightarrow{t \to -t} x[-0.5t-0.5] \neq x[-0.5t-1]$$

Time scaling and time reversal are commutative, so we may change their order.

**SOL 1.2.46** Option (B) is correct.

In multiple transformation, we first do shifting then time scaling. From y(t), we can see that x(t) is shifted to right by 4 time units to get x(t-4). Then it is time expanded by a factor of 2 to get x(2t-4)







**SOL 1.2.48** Option (C) is correct. From the graphs, we can see that signal has no time shift (because origin is not shifted), so  $t_0 = 0$ . Signal x(t) is magnitude scaled by a factor of -2. Since, y(t) has half duration of x(t), so it is time compressed by a factor of 2.  $W = \frac{1}{2}$ 

$$y(t) = -2x\left(\frac{t}{\frac{1}{2}}\right) = -2x(2t)$$

SOL 1.2.49

Option (B) is correct. The sequence of transformation

 $x(t) \xrightarrow{t \to t/2} x\left(\frac{t}{2}\right) \xrightarrow{t \to t-1} x\left(\frac{t-1}{2}\right) \xrightarrow{-6} - 6x\left(\frac{t-1}{2}\right)$ 

If we change the order of transformation.

$$x(t) \xrightarrow{t \to t-1} x(t-1) \xrightarrow{t \to t/2} x\left(\frac{t}{2} - 1\right) \neq x\left(\frac{t-1}{2}\right)$$

Graphically





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$$\begin{aligned} \theta(t) &= 6\delta(3t+9) = 6\delta[3(t+3)] \\ &= \frac{6}{3}\delta(t+3) \\ &= 2\delta(t+3) \end{aligned} \qquad \delta[a(t+b)] = \frac{1}{a}\delta(t+b) \end{aligned}$$

So, g(t) is an impulse with magnitude of 2 unit at t = -3.

**SOL 1.2.54** Option (B) is correct.

Here we can apply the shifting property of impulse function as below

$$\int_{-\infty}^{\infty} f(t)\,\delta(t-t_0)\,dt = f(t_0)$$

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Thus 
$$x(t) = \int_{-\infty}^{\infty} \delta(t+5)\cos(\pi t) dt = \cos(\pi t) \Big|_{t=-5} = \cos(-5\pi) = -1$$

**SOL 1.2.55** Option (C) is correct. First, fold the signal about t = 0 to get r(-t) and then shift r(-t) toward right to

get r(-t+2) as shown below







The signal  $x_2(t)$  is shown below



Energy of 
$$x_3(t)$$
  $E_3 = \int_{-\infty}^{\infty} |x_3(t)|^2 dt = \int_{0}^{\infty} (1 + e^{-6t})^2 dt$   
 $= \int_{0}^{\infty} (1 + e^{-12t} + 2e^{-6t}) dt = \infty$  (  $x_3$  is unbounded)

So, only  $x_1(t)$  has finite energy.

**SOL 1.2.57** Option (B) is correct.

x(t) = u(t+2) - 2u(t) + u(t-2)

To draw x(t), we observe change in amplitude at different instants.

- 1. First at t = -2, x(t) steps up with amplitude 1.
- 2. At t = 0, another step is added with amplitude of -2. So, the net amplitude

becomes [1 + (-2)] = -1.

3. Similarly at t = 2, a step with amplitude 1 is added which causes net amplitude (-1+1) = 0.

## **SOL 1.2.58** Option (C) is correct.

To sketch x(t), we observe change in amplitude of step signals at different instants of time.

- 1. At t = -3, a step with magnitude -1 is added.
- 2. At t = -1, another step of magnitude +2 is added which causes net magnitude (2-1) = 1.
- 3. At t = 1, a step of magnitude -2 is added so net magnitude becomes (1-2) = -1.
- 4. At t = 3, a step with magnitude 1 is added, Now magnitude is (-1+1) = 0.

### **SOL 1.2.59** Option (B) is correct.

x(t) = r(t+2) - r(t+1) - r(t-1) + r(t-2)

To sketch x(t), we observe change in slope at different instants of time.

- 1. At t = -2, a ramp with slope of 1 is added.
- 2. At t = -1, a ramp with slope of -1 is added, so net slope becomes (-1+1) = 0
- 3. Similarly, at t = 1, a ramp of slope -1 is added with causes net slope (-1+0) = -1
- 4. Again, at t = 2 a ramp of slope 1 is added and the net slope becomes zero.

The correct sketch is



\*\*\*\*\*\*\*\*

## **SOLUTIONS 1.3**

SOL 1.3.1	Option (A) is correct. Period of $x(t)$ ,	$T = \frac{2\pi}{\omega} = \frac{2\pi}{60} = \frac{\pi}{30}$ sec
SOL 1.3.2	Option (C) is correct. Period of $\sin 5t$ ,	$T_1 = \frac{2\pi}{5}$
	Period of $\cos 7t$ ,	$T_2 = \frac{2\pi}{7}$
	Period of $x(t)$ ,	$T = \mathrm{LCM}\left(\frac{2\pi}{5}, \frac{2\pi}{7}\right) = 2\pi$
SOL 1.3.3	Option (D) is correct. Signal $x(t)$ is not period	ic because of the term $5t$ which is aperiodic in nature.
SOL 1.3.4	Option (D) is correct.	

Not periodic because least common multiple of periods of  $\sin 3t$  and  $\sin \sqrt{t}$  is infinite.

**SOL 1.3.5** Option (A) is correct.

Even part of x(t),  $x_e(t) = \frac{1}{2}[x(t) + x(-t)]$ 

This can be obtained graphically in following steps :



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#### Chapter 1

**SOL 1.3.6** Option (C) is correct.

Odd part of x(t),  $x_e(t) = \frac{1}{2}[x(t) + x(-t)]$ 

This can be obtained graphically in following steps :





Even part of x(t),  $x_e(t) = \frac{1}{2}[x(t) + x(-t)]$ 

Signal  $x_e(t)$  is obtained as follows :



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**SOL 1.3.8** Option (C) is correct. This is energy signal because

$$E_{\infty} = \int_{-\infty}^{\infty} x(t) \, dt < \infty = \int_{-\infty}^{\infty} e^{-4t} u(t) \, dt = \int_{0}^{\infty} e^{-4t} \, dt = \frac{1}{4}$$

**SOL 1.3.9** Option (A) is correct. Energy of signal x(t),  $E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt$ 

 $= \int_{-\infty}^{\infty} (1) dt = \infty \qquad \qquad \text{Since } |x(t)| = 1$ 

Energy of x(t) is infinite, therefore this is a power signal not an energy signal. Power of x(t),  $P_x = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} |x(t)|^2 dt = 1$ 

 $=\frac{1}{2}\int_{0}^{\pi/\omega} \left(\frac{1}{2}\cos 2\omega t + \frac{1}{2} + 2\cos \omega t + 1\right) dt$ 

**SOL 1.3.10** Option (A) is correct. Energy of signal x(t),  $E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\pi/\omega}^{\pi/\omega} \frac{1}{4} (\cos \omega t + 1)^2 dt$  $= \frac{2}{4} \int_{0}^{\pi/\omega} (\cos^2 \omega t + 2\cos \omega t + 1) dt$ 

$$2(2)(\omega) \quad 4\omega$$
**SOL 1.3.11** Option (B) is correct.  
First we shift  $x(t)$  and  $y(t)$  to the right by 1 unit, to get  $x(t-1)$  and  $y(t-1)$ 

 $-\frac{1}{3}(\frac{3}{\pi}) - \frac{3\pi}{3\pi}$ 

respectively. Now by adding x(t-1) and y(t-1), we get  $f_1(t)$  as shown below

First we shift x(t) to the right by 1 unit to get x(t-1) and y(t) to the left by 1 unit to get y(t+1). Now, adding x(t-1) and y(t+1) we will get  $f_2(t)$  as shown below



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**SOL 1.3.13** Option (A) is correct. First we shift x(t) to the right by 0.5 unit, and y(t) to the left by 0.5 unit to get x(t-0.5) and y(t+0.5) respectively. Now, adding x(t-0.5) and y(t+0.5) we will get  $f_3(t)$  as shown below



**SOL 1.3.14** Option (D) is correct.

 $f_4(t)$  can be obtained by performing multiple operation on x(t). First delay x(t) by 1 unit, we get x(t-1). Now, time expand x(t-1) by a factor of 2, we get x(t/2-1) or x(0.5t-1). In last step,  $f_4(t)$  can is obtained by multiplying x(0.5t-1) with a constant 1.5. Graphically, these steps are performed as shown below :



**SOL 1.3.15** Option (C) is correct. y(t) = x(10t-5)The sequence of transformation is

$$x(t) \xrightarrow{t \to t-5} x(t-4) \xrightarrow{t \to 10t} x(10t-5)$$

This can be performed in following steps



**SOL 1.3.16** Option (D) is correct. Multiplication of independent variable t by 5 will bring compression on time scale. It may be checked by  $x(5 \times 0.8) = x(4)$ . SOL 1.3.17 Option (A) is correct.Division of independent variable t by 5 will bring expansion on time scale. It may be checked by

$$y(20) = x\left(\frac{20}{5}\right) = x(4)$$

**SOL 1.3.18** Option (C) is correct. Mathematically, the function x(t) can be defined as  $\{t+5,$  for -5 < t < -4

$$x(t) = \begin{cases} -t+5, & \text{for} \quad 4 < t < 5\\ 1, & \text{for} \quad -4 < t < 4 \end{cases}$$
$$y(t) = \frac{dx(t)}{dt} = \begin{cases} 1, & \text{for} \quad -5 < t < -4\\ -1, & \text{for} \quad 4 < t < 5\\ 0, & \text{for} \quad -4 < t < 4 \end{cases}$$

Energy of y(t) is calculated as

$$E_y = \int_{-\infty}^{\infty} |y(t)|^2 dt = \int_{-5}^{-4} (1)^2 dt + \int_{4}^{5} (-1)^2 dt = 2$$

**SOL 1.3.19** Option (D) is correct.  

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt = 2 \int_0^5 x^2(t) dt$$

$$= 2 \int_0^4 (1)^1 dt + 2 \int_4^5 (5-t)^2 dt = 8 + \frac{2}{3} = \frac{36}{3}$$

**SOL 1.3.20** Option (C) is correct. The transformation of x(t) to y(t) is shown as below



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**SOL 1.3.21** Option (A) is correct.  
For an impulse function we have  
$$\int_{-\infty}^{\infty} \delta(t-a) dt = 1, \text{ for } t = a \text{ otherwise } 0.$$

so, 
$$\int_{-1}^{8} [\delta(t+3) - 2\delta(4t)] \, \delta t = \int_{-1}^{8} \delta(t+3) \, dt - 2 \int_{-1}^{8} \delta(4t) \, dt$$

$$= 0 - 2 \int_{-1}^{8} \delta(4t) \qquad \qquad \int_{-\infty}^{\infty} \delta(t-a) dt = 1, \text{ for } t = a$$
$$= -\frac{2}{4} \int_{-1}^{8} \delta(t) = -\frac{1}{2} \qquad \qquad \text{since } \delta(at) = \frac{1}{a} \delta(t)$$

 $\int_{-1}^{8} \delta(t+3) dt = 0 \text{ because } t = -3 \text{ does not exist in the given interval } (-1 < t < 8).$ 

**SOL 1.3.22** Option (C) is correct.  

$$x(t) = 2\delta(2t) + 6\delta[3(t-2)]$$
  
 $= \frac{2}{2}\delta(t) + \frac{6}{3}\delta(t-2)$  since  $\delta a(t-t_0) = \frac{1}{a}\delta(t-t_0)$   
 $= \delta(t) + 2\delta(t-2)$ 

**SOL 1.3.23** Option (A) is correct. From the shifting property of impulse function, we know that

So,  

$$\int_{-\infty}^{\infty} x(t) \,\delta(t-t_0) \,dt = x(t_0)$$

$$y(\tau) = \int_{-\infty}^{\infty} x(\tau) \left[\delta(\tau-2) + \delta(\tau+2)\right] d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) \left[\delta(\tau-2)\right] d\tau + \int_{-\infty}^{\infty} x(\tau) \left[\delta(\tau+2)\right] d\tau$$

$$= x(2) + x(-2)$$

**SOL 1.3.24** Option (D) is correct. Substituting  $at = u \Rightarrow dt = \frac{1}{a} du$ , we get  $\int_{-\infty}^{\infty} \delta(at - b) \sin^{2}(t - 4) dt = \int_{-\infty}^{\infty} \delta(u - b) \sin^{2}(\frac{u}{a} - 4) \frac{du}{a}$   $= \frac{1}{a} \int_{-\infty}^{\infty} \delta(u - b) \sin^{2}(\frac{u}{a} - 4) du$ 

**SOL 1.3.25** Option (C) is correct. x(t) is obtained in following steps :



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**SOL 1.3.28** Option (D) is correct. Figure is as shown below



- **SOL 1.3.29** Option (B) is correct. This is triangle with the same height as  $(\frac{1}{\alpha}) \operatorname{tri}(\frac{x}{\alpha})$ , but 1/4 times the base width. Therefore, its area is 1/4 times as that of area of  $\delta(x)$  or 1/4.
- **SOL 1.3.30** Option (B) is correct.

This is a triangle with the same height as  $\delta(x)$  but 1/6 times the base width. The fact that the factor is -6 instead of 6, just, means that the triangle is reversed in time which does not change its shape or area. Thus its area is 1/6 times as that of  $\delta(x)$  or 1/6. The area of function

$$\delta(bx) = \lim_{a \to 0} \frac{1}{a} \operatorname{tri}\left(\frac{bx}{a}\right), \ a > 0 \text{ is } \frac{1}{|b|}$$

**SOL 1.3.31** Option (C) is correct.

$$\begin{aligned} x(t) &= 2 \operatorname{tri}\left[2\left(t-1\right)\right] + 6 \operatorname{rect}\left(\frac{t}{4}\right) \\ x\left(\frac{3}{2}\right) &= 2 \operatorname{tri}\left[2\left(\frac{3}{2}-1\right)\right] + 6 \operatorname{rect}\left(\frac{3}{8}\right) \\ &= 2 \operatorname{tri}\left(1\right) + 6 \operatorname{rect}\left(\frac{3}{8}\right) = 2\left[1-(1)\right] + 6 = 6 \end{aligned}$$

**SOL 1.3.32** Option (A) is correct. The figure is as shown below :



- **SOL 1.3.33** Option (D) is correct. v(t) is sum of 3 unit step signal starting from 1, 2, and 3, all signal ends at 4.
- **SOL 1.3.34** Option (B) is correct. Unit step function u(t) and its folded version u(-t) are shown in the figures below



Now, by shifting u(-t) to the right by a units and b units, we get u(a-t) and u(b-t) respectively.



Similarly, by shifting u(t) to the right by a units and b units, we get u(t-a)and u(t-b).



From the above graphs, we can see that

$$v(t) = u(t-a) - u(t-b)$$
  
$$v(t) = u(b-t) \times u(t-a)$$



Option (B) is correct.

The ramp function is shown as



and,

Signal r(t-4) and r(t-6) are obtained by shifting r(t) towards right by 4 units and 6 units respectively. Now we subtract r(t-6) from r(t-4) to get x(t).



**Alternate Method :** 

We have	$r(t-4) = \int t - 4,$	t > 4
	$\begin{bmatrix} 0 \\ 0 \end{bmatrix} 0,$	t < 4
and	$r(t-6) = \int^{t-6} dt dt$	t > 6
	$\begin{bmatrix} r & 0 \end{bmatrix} \begin{bmatrix} 0 \end{bmatrix},$	t < 6

Now 
$$r(t-4) - r(t-6) = \begin{cases} t-4, & 4 < t < 6\\ t-4-t+6, & t > 6\\ 0, & t < 4 \end{cases}$$
$$= \begin{cases} t-4, & 4 < t < 6\\ 2, & t > 6\\ 0, & t < 4 \end{cases}$$

**SOL 1.3.36** Option (C) is correct.

To obtain the expression for x(t), we note the change in amplitude and slope at different instants of time and write expression for each change. The steps are as follows :

1. At t = 0, the function steps from 0 to 3, for a change in amplitude of 3. Also the slope of function changes from 0 to -3, for a change in slope of -3; so we write

$$x_1(t) = (3-0) u(t-0) + (-3-0) (t-0) u(t-0)$$
  
=  $3u(t) - 3tu(t) = 3(1-t) u(t)$ 

2. At t = 1, the function steps from 0 to 1.5, for a change in amplitude of 1.5. Also the slope of function changes from -3 to -1.5, for a change in slope of 1.5; so we write

$$x_2(t) = 1.5u(t-1) + 1.5(t-1)u(t-1)$$
  
= 1.5u(t-1) + 1.5tu(t-1) - 1.5u(t-1)  
= 1.5tu(t-1)

3. At t = 3, the function steps up from -1.5 to 0, for a change in amplitude of 1.5. Also the slope of function changes from -1.5 to 0, for a change in slope of 1.5; so we write

$$\begin{aligned} x_3(t) &= 1.5u(t-3) + 1.5(t-3)u(t-3) \\ &= 1.5u(t-3) + 1.5tu(t-3) - 4.5u(t-3) \\ &= 1.5tu(t-3) - 3u(t-3) \\ &= 1.5(t-2)u(t-3) \end{aligned}$$

Hence the equation for x(t) is

$$\begin{aligned} x(t) &= x_1(t) + x_2(t) + x_3(t) \\ &= 3(1-t)u(t) + 1.5tu(t-1) + 1.5(t-2)u(t-3) \end{aligned}$$

### **SOL 1.3.37** Option (A) is correct.

To obtain the waveform for x(t), we observe change in magnitude of unit step signals at different instants of time.

- 1. At t = -1, a step with magnitude 1 is added, so magnitude at t = -1 is 1.
- 2. At t = 1, another step of magnitude -2 is added, so net amplitude becomes (1-2) = -1
- 3. At t = 3, a step of magnitude 1 is added which causes net magnitude (-1+1) = 0

### **Alternate Method :**

From the expression we get

```
For -1 < t < 1, x(t) = 1
For 1 < t < 3, x(t) = -1
For t > 3, x(t) = 0
```

#### Option (D) is correct. SOL 1.3.38

Rearranging the given expression

x(t) = -2u(t+2) + u(t+1) + u(t)

The sketch of x(t) is obtained using following steps :

- At t = -2, a step of magnitude -2 is added, so magnitude at t = -2 is -21.
- At t = -1, another step of magnitude 1 is added which causes net magnitude 2.to become (-2+1) = -1
- 3. At t = 0, another step of magnitude 1 is added, the net amplitude now becomes (-1+1) = 0.

#### **Alternate Method:**

For -2 < t < 1, x(t) = -2For -1 < t < 0, x(t) = -1For 0 < t, x(t) = 0

#### Option (B) is correct. SOL 1.3.39

By observing both the change in amplitude and change in slope, we get x(t) as following :

- 1. At t = 1, a ramp of slope 2 is added, so the net slope of function becomes (0+2) = 2
- At t=2, a ramp of slope -2 is added which causes net slope to becomes 2. (2-2) = 0
- 3. At t = 3, another ramp of slope 2 is added, now net slope of function becomes (0+2) = 2

#### **Alternate Method :**

For 1 < t < 2, x(t) = 2(t-1)For 2 < t < 3, x(t) = 2For 3 < t, x(t) = 2t - 2

Option (D) is correct.

Rewriting the x(t) as below

x(t) = -tu(t) + (t-1)u(t-1) + 2u(t-1) - u(t-2)

- 1. At t = 0, a ramp of slope -1 is added.
- At t = 1, another ramp of slope 1 is added, so net slope at this instant becomes 2.(-1+1) = 0
- 3. At t = 1, a step of amplitude 2 is added, so amplitude of x(t) becomes

SOL 1.3.40

$$(-1+2) = 1$$

- 4. At t = 2 another step of amplitude -1 is added which causes net amplitude to become (1 1) = 0
- **SOL 1.3.41** Option (A) is correct. We may represent y(t) as the superposition of 4 rectangular pulses as follows

$$y(t) = y_1(t) + y_2(t) + y_3(t) + y_4(t)$$

 $y_1(t)$ ,  $y_2(t)$ ,  $y_3(t)$  and  $y_4(t)$  are the time shifted and time scaled version of function x(t) with different factors.

In general  $y_i(t) = x(a_i t - b_i)$ i = 1, 2, 3, 4 $y_1(t) = x(a_1t - b)$  $y_1(0) = x(a_1 \times 0 - b_1) = x(-1)$ For t = 0,  $\Rightarrow$  $a_1 \times 0 - b_1 = -1$  $b_1 = 1$  $y_1(4) = x(a_1 \times 4 - b_1) = x(1)$ For t = 4,  $a_1 \times 4 - b_1 = 1$  $\Rightarrow$  $4a_1 = 1 + b_1 \Rightarrow a_1 = 1/2$  $y_1(t) = x\left(\frac{1}{2}t - 1\right)$  $y_2(t) = x(a_2t - b_2)$  $y_2(1) = x(a_2 \times 1 - b_2) = x(-1)$ For t = 1,  $\Rightarrow$  $a_2 - b_2 = -1$ ...(i)  $y_2(4) = x(a_2 \times 4 - b_2) = x(1)$ For t = 4,  $4a_2 - b_2 = 1$  $\Rightarrow$ ...(ii) Solving equation (i) and (ii), we get a = 2/3 and b = 5/3 $y_2(t) = x\left(\frac{2}{3}t - \frac{5}{3}\right)$ Thus, Similarly, we can obtain  $y_3(t)$  and  $y_4(t)$  also  $y_3(t) = x(t-3)$  $y_4(t) = x(2t-7)$ 

Accordingly, we may express the staircase signal y(t) in terms of the rectangular pulses x(t) as follows:

SOL

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$$y(t) = x\left(\frac{1}{2}t-1\right) + x\left(\frac{2}{3}t-\frac{5}{3}\right) + x(t-3) + x(2t-7)$$
**1.3.42** Option (B) is correct.  

$$x_1(t) \text{ can be obtained using following methodology}$$
**1.** At  $t = 0$ , slope changes from 0 to 2, so we write  

$$x_1'(t) = 2tu(t)$$
**2.** At  $t = 1$ , slope change from 2 to  $-2$  for a change of  $-4$  in slope; so we write  

$$x_1''(t) = -4(t-1)u(t-1)$$
**3.** At  $t = 2$ , slope changes from  $-2$  to 0 for a change of 2 in slope; so we write  

$$x_1'''(t) = 2(t-2)u(t-2)$$
Thus,

$$\begin{aligned} x(t) &= x_1'(t) + x_1''(t) + x_1'''(t) \\ &= 2tu(t) - 4(t-1)u(t-1) + 2(t-2)u(t-2) \end{aligned}$$

**SOL 1.3.43** Option (B) is correct.

The expression for periodic waveform is

$$x(t) = \sum_{k=-\infty}^{\infty} x_1(t - kT_0)$$

Here,  $T_0 = 2$ , therefore

$$x(t) = \sum_{k=-\infty}^{\infty} x_1(t-2k)$$

\*\*\*\*\*\*\*

# **SOLUTIONS 1.4**

SOL 1.4.1	Option (D) is correct. A signal conveys information on the nature of physical phenomenon			
SOL 1.4.2	Option (A) is correct. $x(t) = \cos(1.2\pi t) + \cos(2\pi t) + \cos(2.8\pi t)$ Frequency of $\cos(1.2\pi t)$ , $f_1 = 0.6$ Hz Frequency of $\cos(2\pi t)$ , $f_2 = 1$ Hz Frequency of $\cos(2\pi t)$ , $f_3 = 1.4$ Hz Fundamental Frequency of $x(t)$ will be greatest common divisor of $f_1$ , $f_2$ , $f_3$ $f = \text{GCD}(f_1, f_2, f_3)$ $= 0.2$ Hz	$\pi \pi \cdot t$		
SOL 1.4.3	Option (A) is correct. We have $x(t) = \cos(200\pi t) + 0.5\cos(40\pi t)\cos(200\pi t)$ $= \cos(200\pi t) + \frac{1}{4}\cos 240\pi t + \frac{1}{4}\cos(360\pi t)$ Fundamental frequency of $(\cos 200\pi t)$ , $f_1 = 100$ Hz $2\pi f_1 = 200\pi$ Fundamental frequency of $(\cos 240\pi t)$ , $f_2 = 120$ Hz $2\pi f_2 = 240\pi$ Fundamental frequency of $(\cos 360\pi t)$ , $f_3 = 180$ Hz $2\pi f_3 = 360\pi t$ Fundamental frequency of $x(t)$ is greatest common devisor of $f_1, f_2$ and $f_3$ , i. e. $f = \text{GCD}(f_1, f_2, f_3) = 20$ Hz			
SOL 1.4.4	Option (C) is correct. $x(t) = 2\sin(2\pi t) + 3\sin(3\pi t)$ Period of $\sin(2\pi t)$ , $T_1 = \frac{2\pi}{2\pi} = 1$ sec Period of $\sin(3\pi t)$ , $T_2 = \frac{2\pi}{3\pi} = \frac{2}{3}$ sec Ratio $\frac{T_1}{T_2} = \frac{m}{n} = \frac{1}{(2/3)} = \frac{3}{2}$ Period of $x(t)$ , $T = \text{LCM}\left(1, \frac{2}{3}\right) = 2$			
SOL 1.4.5	Option (B) is correct. We have $f(t) = \cos\left[\frac{\pi}{4}(t-1)\right]$ Period of $f(t)$ , $T = \frac{2\pi}{\omega} = \frac{2\pi}{(\pi/4)} = 8 \sec$			

SOL 1.4.6 Option (A) is correct.  $x_1(t) = 2\sin\pi t + \cos 4\pi t$  $T_{11} = \frac{2\pi}{\pi} = 2$ Period of  $\sin \pi t$ ,  $T_{12} = \frac{2\pi}{4\pi} = \frac{1}{2}$ Period of  $\cos 4\pi t$ ,  $\frac{T_{11}}{T_{12}} = \frac{2}{(1/2)} = 4$  (rational) Since ratio of  $T_{11}$  and  $T_{12}$  is rational,  $x_1(t)$  is periodic.  $x_2(t) = \sin 5\pi t + 3\sin 13\pi t$  $T_{21} = \frac{2\pi}{5\pi} = \frac{2}{5}$ Period of  $\sin 5\pi t$ ,  $T_{22} = \frac{2\pi}{13\pi} = \frac{2}{13}$ Period of  $\sin 13\pi t$ ,  $\frac{T_{21}}{T_{22}} = \frac{(2/5)}{(2/13)} = \frac{13}{5}$  (rational) Since ratio of  $T_{21}$  and  $T_{21}$  is rational,  $x_2(t)$  is also periodic. Option (B) is correct. SOL 1.4.7 The sum of two sinusoids is periodic if ratio of their periods is rational. Option (A) is correct. SOL 1.4.8 A signal is said to be periodic if it repeats at regular interval. If x(t) is periodic with period  $T_0$  it must satisfies.  $x(t+T_0) = x(t)$ Option (B) is correct. SOL 1.4.9  $x_1(t) = e^{j20t}$ We have  $T_1 = \frac{2\pi}{20} = \frac{\pi}{10}$ Period of  $x_1(t)$ ,  $x_2(t) = e^{-(2+j)t}$ Since,  $\frac{2\pi}{(2+j)}$  is not rational, so  $x_2(t)$  is not periodic. Option (A) is correct. SOL 1.4.10  $x_1(t) = \sin(10\pi t) + \sin(20\pi t)$  $(\mathbf{A})$ Period of  $\sin(10\pi t)$ ,  $T_{11} = \frac{2\pi}{10\pi} = \frac{1}{5}$  $T_{12} = \frac{2\pi}{20\pi} = \frac{1}{10}$ Period of  $\sin(20\pi t)$ ,  $\frac{T_{11}}{T_{12}} = \frac{1/5}{1/10} = 2$  (rational) Ratio Since ration of  $T_{11}$  and  $T_{12}$  is rational,  $x_1(t)$  is periodic. (B) $x_2(t) = \sin(10t) + \sin(20\pi t)$  $T_{21} = \frac{2\pi}{10} = \frac{\pi}{5}$ Period of  $\sin(10t)$ ,

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	Period of $\sin(20\pi t)$ ,	$T_{22} = \frac{2\pi}{20\pi} = \frac{1}{10}$					
	Ratio,	$rac{T_{21}}{T_{22}} = rac{\pi/5}{1/10} = 2\pi$	(not rational)				
	Since $T_{21}/T_{22}$ is not rational, $x_2(t)$ is not periodic. Similarly, we can check for option (C) and (D) also. Both are aperiodic.						
SOL 1.4.11	Option (D) is correct.						
	Period of $x(t)$ ,	$T = \frac{2\pi}{\omega} = \frac{2\pi}{0.8\pi} = 2.5 \mathrm{se}$	с				
SOL 1.4.12	Option (D) is correct.	Option (D) is correct.					
	x(t) =	$x_1(t) + jx_2(t)$					
	A complex valued signa	l always possess conjugate	symmetry.				
SOL 1.4.13	Option (A) is correct.						
	$\Psi(t) = 1$	$\frac{f(t) + f(-t)}{f(-t)}$					
	$\Psi(-t) = \int_{t}^{t} \Psi(t) = \int_{t}^{t} \Psi(t) dt$	$\frac{f(-t) + f(t)}{\mu(-t)}$	Thus $\mathcal{U}(t)$ is an even function				
	Since $\Psi(t) =$	$\Psi(-\iota)$	Thus $\Psi(t)$ is an even function.				
SOL 1.4.14	Option (B) is correct. We have $m(t)$	$A \cos(\omega t + \phi)$					
	We have $x(t) = A\cos(\omega t + \phi)$ We know that most of the periodic signals are never signal, $x(t)$ is also a periodic						
	we know that most of the periodic signals are power signal. $x(t)$ is also a periodic signal and has finite power.						
	0 I n —	$\underline{A^2}$					
001 4 4 45	$p_x -$	2					
<b>50L</b> 1.4.15	Option (D) is correct.						
	Average power of signal is given by $1 \int f^{T/2} = f(x) f^2 x^2$						
	$P = \lim_{T  o \infty} rac{1}{T} \int_{-T/2}  x(t) ^2 dt$						
	<b>Note :</b> If $x(t)$ is periodic, then T has finite value and above expression becomes as						
	$P = rac{1}{T} \int_{T/2}^{T/2}  x(t) ^2 dt = rac{1}{T} \int_{0}^{T}  x(t) ^2 dt$						
SOL 1.4.16	16 Option (C) is correct. Energy of a power signal is infinite while the power of an energy signal is zero.						
SOL 1.4.17	Option (A) is correct.						
	s(t) =	$8\cos\left(\frac{\pi}{2} - 20\pi t\right) + 4\sin 15\pi$	t				
	=	$8\sin 20\pi t + 4\sin 15\pi t$					
	Here $A_1 = 8$ and $A_2 = 4$	Thus power is					
	$P = \frac{A_1^2}{2} + \frac{A_2^2}{2} = \frac{8^2}{2} + \frac{4^2}{2} = 40$						
SOL 1.4.18	Option (B) is correct.	- <b>-</b>					
	A bounded signal always possesses some finite energy.						
	$E = \int_{-t_0}^{t_0}  g(t) ^2$	$ t ^2  dt < \infty$					

Sample Chapter GATE CLOUD Signals & System by Kanodia **SOL 1.4.19** Option (B) is correct.

Let E be the energy of f(t) and  $E_1$  be the energy of f(2t), then

 $E = \int_{-\infty}^{\infty} [f(t)]^2 dt$  $E_1 = \int_{-\infty}^{\infty} [f(2t)]^2 dt$ 

and

Substituting 2t = p we get

$$E_1 = \int_{-\infty}^{\infty} [f(p)]^2 \frac{dp}{2} = \frac{1}{2} \int_{-\infty}^{\infty} [f(p)]^2 dp = \frac{E}{2}$$

**SOL 1.4.20** Option (C) is correct.

If a function f(t) is shifted to right side by  $t_0$  units, then the shifted function is expressed as  $f(t-t_0) u(t-t_0)$ . Let, f(t) = t+2



If we write, x(t) = f(t) u(t-1)For t = 0 x(0) = f(0) = 2But, x(0) = 0 (In the graph)

So  $f(t) u(t - t_0)$  is not correct expression for shifted signal.



The plot of given signal x(t) is shown below



First reflect the signal about the vertical axis to obtain x(-t). Then shift x(-t) towards right by 1 unit to get x(-t+1). Both operation is shown below



We know that  $\delta(t) x(t) = x(0) \delta(t)$  and  $\int_{-\infty}^{\infty} \delta(t) = 1$ 

Let 
$$x(t) = \cos(\frac{3}{2}t)$$
, then  $x(0) = 1$ 

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Now 
$$\int_{-\infty}^{\infty} \xi(t) x(t) = \int_{-\infty}^{\infty} g(0) \delta(t) dt = \int_{-\infty}^{\infty} \xi(t) dt = 1$$
**Sol 1.4.26** Option (B) is correct.  
We know that
$$\int_{-\infty}^{\infty} x(t) \delta(t-t_0) = x(t_0)$$
so 
$$\int_{-\infty}^{\infty} \delta(t - \frac{\pi}{6}) 6\sin(t) dt = 6\sin(t)|_{\pi=\pi/6}$$
Here  $x(t) = 6\sin t$ ,  $t_0 = \frac{\pi}{6}$   
 $= 6\sin(\frac{\pi}{6})$   
 $= 6 \times \frac{1}{2} = 3$ 
**Sol 1.4.27** Option (A) is correct.  
 $x(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} t^2 e^{-t/2} \delta(1-2t) dt$   
Let,  $1 - 2t = \alpha \rightarrow t = \left(\frac{\alpha + 1}{2}\right)$  and  $dt = -\frac{1}{2} d\alpha$   
Now  $x(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \left(\frac{\alpha + 1}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) (\alpha) \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \left(e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \left(e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \left(e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha \int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$   
 $= \frac{1}{2\sqrt{2\pi}} \left(\frac{x}{2}\right)^2 e^{-\frac{1}{2}\left(\frac{\alpha + 1}{2}\right)^2} \delta(\alpha) d\alpha$   
 $\int_{0}^{\infty} f(t) dt = \int_{0}^{0} tu(t) dt = \frac{t}{2}$   
 $x_{0}(t) = \frac{x(t) - x(-t)}{2}$   
Here  $g(t) = u(t)$   
Thus  $x_{0}(t) = \frac{u(t) + u(-t)}{2} = \frac{1}{2}$   
 $x_{0}(t) = \frac{u(t) - u(-t)}{2} = \frac{x(t)}{2}$   
**Sol 1.4.30** Option (D) is correct.  
At  $t = 1$ , signal steps up from 0 \rightarrow 1, so  
 $w_{1}(t) = (2 - 1) u(t - 2) = u(t - 2)$   
At  $t = 3$ , signal steps up from 1 \rightarrow 2, so  
 $w_{1}(t) = (2 - 1) u(t - 2) = u(t - 2)$   
At  $t = 3$ , signal steps up from 2 \rightarrow 3, so

$$v_{3}(t) = (3-2) u(t-3) = u(t-3)$$
  
At  $t = 4$ , signal steps down from  $3 \to 0$ , so  
$$v_{4}(t) = (0-3) u(t-4) = -3u(t-4)$$
$$v(t) = v_{1}(t) + v_{2}(t) + v_{3}(t) + v_{4}(t)$$
$$= u(t-1) + u(t-2) + u(t-3) - 3u(t-4)$$

For detailed discussion please refer to methodology of section 1.6 of the book GATE GUIDE Signals & Systems by same authors.

$$\begin{array}{c} r(t) \xrightarrow{\text{differentiation}} u(t) \xrightarrow{\text{differentiation}} \delta(t) \\ \text{(Ramp)} & \text{(Step)} \end{array} \xrightarrow{\text{(Impulse)}} tu(t) \xrightarrow{\text{differentiation}} u(t) \xrightarrow{\text{differentiation}} \delta(t) \end{array}$$

Given Function is

 $f(t) = -\delta(t-1) - \delta(t-2) + \delta(t-3) + \delta(t-4) - \delta(t-5) + 2\delta(t-6) - \delta(t-7)$ In-terms of ramp function f

$$(t) = -tu(t-1) - tu(t-2) + tu(t-3) + tu(t-4) - tu(t-5) + 2tu(t-6) - tu(t-7)$$

(A) 
$$v(t) = u(t-1) - u(t-3)$$
 (A  $\rightarrow$  3)

(B) 
$$v(t) = \lim_{a \to 0} \delta(t-1)$$
 (B  $\rightarrow$  4)  
(C)  $v(t) = u(t+1)$  (C  $\rightarrow$  1)

C) 
$$v(t) = u(t+1)$$
 (C  $\rightarrow$  1)

(D) 
$$v(t) = u(t) - 2u(t-1) + 2u(t-2) - 2u(t-3) + ...$$
 (D  $\rightarrow$  2)

Option (C) is correct. SOL 1.4.33

At t = 0, f(t) step up from  $0 \rightarrow 1$ , so we write

$$f_1(t) = (1-0)u(t-0) = u(t)$$

At 
$$t = 1$$
,  $f(t)$  steps up from  $1 \rightarrow 2$ , so we write

$$f_2(t) = (2-1)u(t-1) = u(t-1)$$

At t = 2 slope changes from  $0 \rightarrow 1$  so we write

Now,

$$f_3(t) = (1-0)(t-2)u(t-2)$$
  

$$f(t) = f_1(t) + f_2(t) + f_3(t)$$
  

$$= u(t) + u(t-1) + (t-2)u(t-2)$$

For detailed discussion please refer to methodology of section 1.6 on page 37, given in the book GATE GUIDE Signals & Systems by the same authors.

SOL 1.4.34 Option (B) is correct.



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Chapter 1





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